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# Chemical and enzyme kinetics

D. Gonze & M. Kaufman

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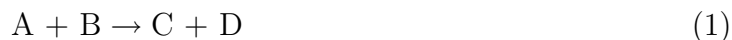
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# 1 Definitions

## 1.1 Reaction rate

Consider the chemical reaction that transforms the substrates A and B into the products C and D:



The variation in time of the concentration of the substrates ( $A$  and  $B$ ) and the products ( $C$  and  $D$ ),

$$\frac{dA}{dt}, \frac{dB}{dt}, \frac{dC}{dt}, \text{ and } \frac{dD}{dt} \quad (2)$$

is determined by the rate at which the reaction proceeds.

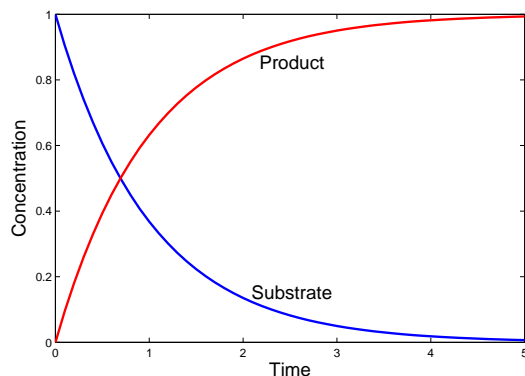


Figure 1: Time evolution of the concentration of the substrate and product.

For a chemical reaction to occur, the reacting species must collide, have sufficient energy and be well oriented. The number of collisions is proportional to the concentration of the reacting species. For the reaction (1), the rate law is given by the **mass action law**:

$$v = kAB \quad (3)$$

Not all collisions are reactive. The rate constant  $k$  accounts for the probability that the molecules are well oriented and have sufficient energy to react.

The variation in time of the concentration of the substrates and the products is given by

$$\frac{dA}{dt} = \frac{dB}{dt} = -kAB \text{ and } \frac{dC}{dt} = \frac{dD}{dt} = kAB \quad (4)$$

The sign in the right-hand side of these equations stands for the fact that, each time the reaction proceeds, one molecule (mole) of A (and B) disappears while one molecule (mole) of C (and D) appears.

More generally, for an (elementary) reaction in which  $m$  molecules of A react with  $p$  molecules of B and in which the products (C and D) do not affect the reaction rate:



the rate law is:

$$v = kA^m B^p \quad (6)$$

Note that the sum  $m + p$  is called the **order of a reaction**.

Consider now for example the following reaction:



According to Eq. (6), the rate of this reaction is:

$$v = kA^3 B \quad (8)$$

When we write the evolution of the concentration of A, we must take into consideration the fact that each time this reaction occurs, only two molecules of A are transformed (one is conserved). So, the variation of A is given by:

$$\frac{dA}{dt} = -2v = -2kA^3 B \quad (9)$$

The coefficient “2” is the balance for the species A in reaction (58) and the sign “-” stands because, globally, A is consumed. Since  $v$  must have the unit [concentration]/[time], the units of  $k$  depend on the order of the reaction.

In the general case, for a reaction in which for each  $n$  molecules (moles) of X transformed  $p$  molecules (moles) are recovered at the end:



the evolution equation for the concentration of X is:

$$\frac{dX}{dt} = \eta v \text{ with } \eta = p - n \quad (11)$$

$\eta$  is called the **stoichiometric coefficient**. This coefficient is positive if, globally, the species is produced ( $p > n$ ) and negative if the species is consumed ( $n > p$ ).

For example, for the following reaction:



the stoichiometric coefficients of the different species are:

$$\eta_A = 3 - 1 = 2, \eta_B = 0 - 2 = -2, \eta_C = 1 - 0 = 1. \quad (13)$$

and the evolution equations are:

$$\frac{dA}{dt} = 2kAB^2, \frac{dB}{dt} = -2kAB^2, \frac{dC}{dt} = kAB^2 \quad (14)$$

## 1.2 Examples

### 1st-order kinetics

Consider the reaction of 1st-order:



or



By definition (eq 2), the rate of this reaction is

$$v = kA \quad (17)$$

and the time evolution of the concentration of the substrate A is:

$$\frac{dA}{dt} = -kA \quad (18)$$

After integration, we find:

$$A(t) = A_0 e^{-kt} \quad (19)$$

where  $A_0$  is the initial concentration of substrate A ( $A_0 = A(0)$ ).

We observe an exponential decrease of the concentration of A with time:

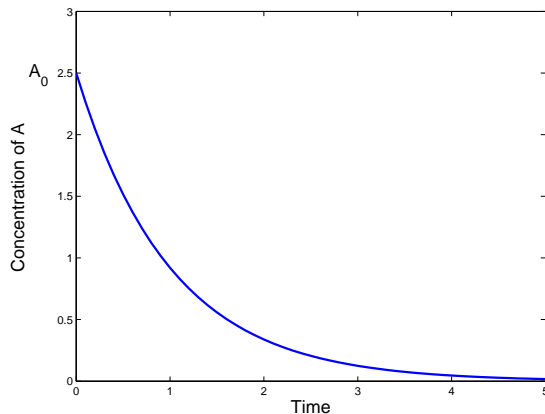
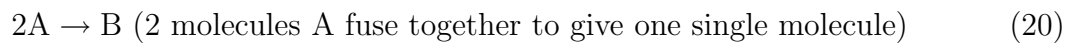


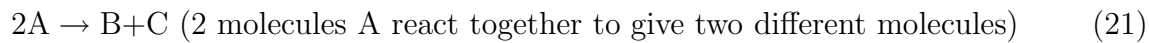
Figure 2: 1st-order kinetics: exponential decrease of the concentration of substrate A.

## 2nd-order kinetics

Let's take now the reaction:



or



Its rate is:

$$v = kA^2 \quad (22)$$

and the time evolution of the substrate A is

$$\frac{dA}{dt} = -2kA^2 \quad (23)$$

After integration, we find:

$$A(t) = \frac{A_0}{1 + 2A_0kt} \quad (24)$$

where  $A_0$  is the initial concentration of substrate A.

Here, we observe an hyperbolic decrease of the concentration of A with time:

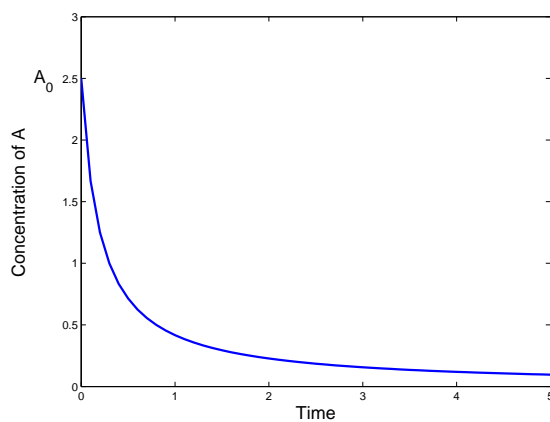
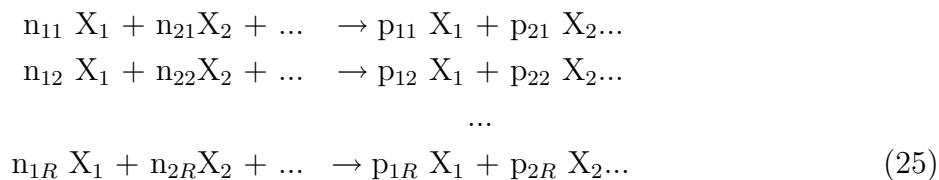


Figure 3: 2nd-order kinetics: hyperbolic decrease of the concentration of substrate A.

### 1.3 System of chemical reactions

We are usually interested by systems of coupled chemical reactions.



The variation of a given compound  $X_i$  involved in  $R$  reactions is defined by:

$$\frac{dX_i}{dt} = \sum_{r=1}^R \eta_{ir} v_r = \eta_{i1} v_1 + \eta_{i2} v_2 + \dots + \eta_{iR} v_R \tag{26}$$

where

$$v_r = \text{rate of reaction } r \text{ (with } r = 1, 2, \dots, R): v_r = k_r \prod_i X_i^{n_{ir}}.$$

$$\eta_{ir} = p_{ir} - n_{ir} = \text{stoichiometric coefficient of compound } X_i \text{ in reaction } r.$$

We illustrate this on the following example:

$r$	reaction	rate	$\eta_{Xr}$	$\eta_{Yr}$
1	$A \xrightarrow{k_1} X$	$v_1 = k_1 A$	$\eta_{X1} = 1$	$\eta_{Y1} = 0$
2	$B + X \xrightarrow{k_2} Y + C$	$v_2 = k_2 B X$	$\eta_{X2} = -1$	$\eta_{Y2} = 1$
3	$2X + Y \xrightarrow{k_3} 3X$	$v_3 = k_3 X^2 Y$	$\eta_{X3} = 1$	$\eta_{Y3} = -1$
4	$X \xrightarrow{k_4} D$	$v_4 = k_4 X$	$\eta_{X4} = -1$	$\eta_{Y4} = 0$

The evolution equations for X and Y are given by (see eq. 26) :

$$\begin{cases} \frac{dX}{dt} = \eta_{X1} v_1 + \eta_{X2} v_2 + \eta_{X3} v_3 + \eta_{X4} v_4 \\ \frac{dY}{dt} = \eta_{Y1} v_1 + \eta_{Y2} v_2 + \eta_{Y3} v_3 + \eta_{Y4} v_4 \end{cases} \tag{27}$$

By substituting the values of  $\eta_{Xi}$ ,  $\eta_{Yi}$  and  $v_i$  (see table here above), these equations become:

$$\begin{cases} \frac{dX}{dt} = k_1 a - k_2 b X + k_3 X^2 Y - k_4 X \\ \frac{dY}{dt} = k_2 b X - k_3 X^2 Y \end{cases} \tag{28}$$

## 1.4 Chemical equilibrium

Often, chemical reactions are not completely irreversible and the transformation of the products back to the substrates is possible. It is then more precise to write:



In general, the concentration of the various substrates and products tend to the equilibrium concentration characterized by the equilibrium constant:

$$K_{eq} = \frac{C_{eq}D_{eq}}{A_{eq}B_{eq}} \quad (30)$$

NB: It is not the case if one of the compound is volatile or forms a precipitate or is consumed in other chemical reaction (ex: metabolic pathways), or is extracted from the medium (ex: translocation in the nucleus of the cell).

When we write the evolution equation for a compound of such a reversible reaction, we get two terms, one for each reaction:

$$\frac{dA}{dt} = -k_1AB + k_{-1}CD \quad (31)$$

At the equilibrium, we have:

$$\overrightarrow{v} = \overleftarrow{v} \quad (32)$$

$$k_1A_{eq}B_{eq} = k_{-1}C_{eq}D_{eq} \quad (33)$$

$$\frac{k_1}{k_{-1}} = \frac{C_{eq}D_{eq}}{A_{eq}B_{eq}} = K_{eq} \quad (34)$$

**Note:** In biology we often need to describe the kinetics of complex formation (such as the dimerization of proteins or the binding of a substrate to an enzyme or a ligand to a receptor):



In this case, the equilibrium is determined by the dissociation constant  $K_D = k_d/k_a$ .



## 2 Enzyme kinetics

### 2.1 Enzymes

Enzymes are catalysts (generally proteins) that help to convert other molecules called substrates, into products, but they themselves are not changed by the reaction. Their most important features are catalytic power, specificity and regulation. Enzymes accelerate the conversion of substrates into products by lowering the free energy of activation of the reaction. For example, enzymes may aid in converting charge repulsions and allowing reacting molecules to come into contact for the formation of new chemical bonds. Or, if the reaction requires breaking of an existing bond, the enzyme may exert a stress on a substrate molecule, rendering a particular bond easily broken. Enzymes are particularly efficient at **speeding up** biological reactions, giving increase in speed up to 10 million times or more. They are also **highly specific**, usually catalysing the reaction of only one particular substrate or closely related substrates. Finally, they are typically **regulated** by various positive and negative feedback systems, thus allowing precise control over the rate of reaction.

An example of enzymatic reaction is the first reaction of the glycolysis, catalysed by the enzyme hexokinase (fig. 4):

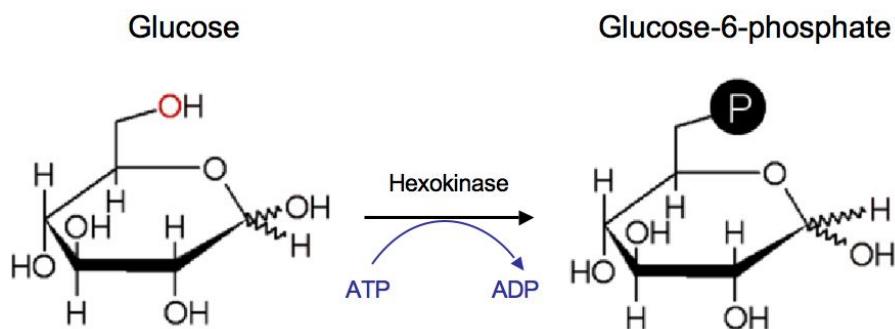
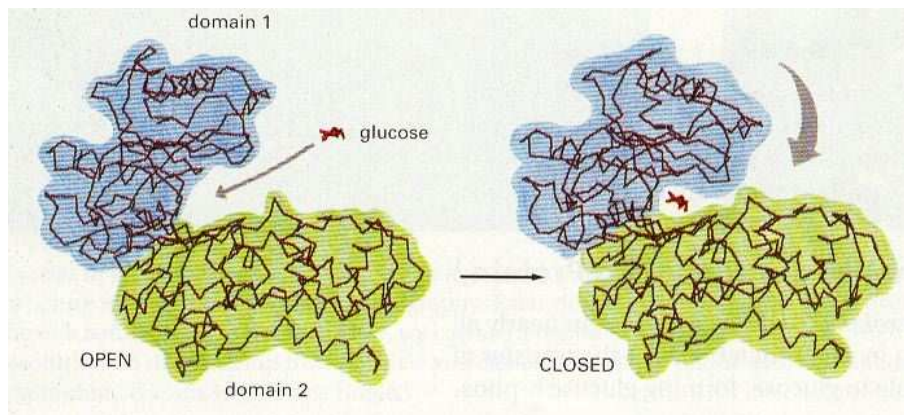


Figure 4: Hexokinase.

Enzymes accelerate reaction by stabilizing transition states of intermediary reactants, thereby lowering the activation energy required for the reaction (Fig. 5).

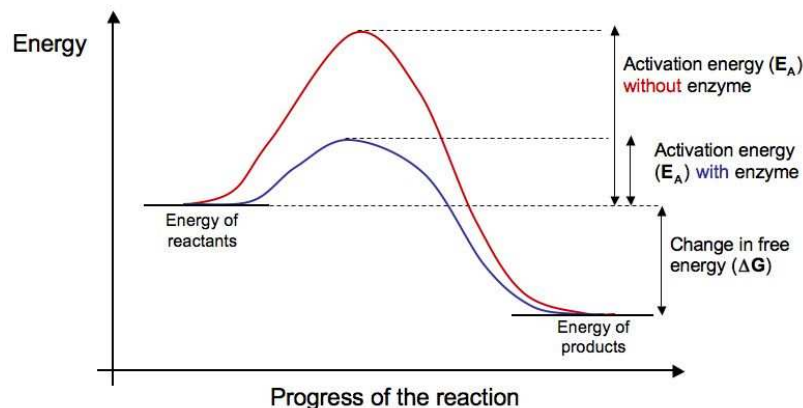


Figure 5: Activation Energy.

One of the first things to realize about enzyme reactions is that they do not follow the law of mass action directly. As the concentration of substrate is increased, the rate of the reaction increases only to a certain extent, reaching a maximal reaction velocity at high substrate concentration. This is in contrast with the mass action law, which, when applied directly to the reaction with the enzyme predicts that the reaction velocity increases linearly as the substrate increases. We describe here the most common mechanisms to explain this saturation in speed (i.e. Michaelis-Menten and Briggs-Haldane equations), as well as the effect of inhibitors and activators on the kinetics. We will also discuss the Hill function, used to describe enzyme kinetics in the presence of cooperativity, as well as the kinetics of allosteric enzymes.



Figure 6: From left to right: Leonor Michaelis, Maud Menten, and Archibald Hill

## 2.2 Equilibrium approximation: Michaelis-Menten equation

Based on experimental observations, Michaelis and Menten (1913) have proposed the following mechanism for the enzyme-catalysed biochemical reactions:

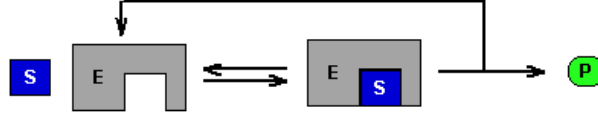
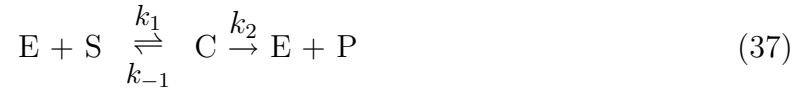


Figure 7: Michaelis-Menten mechanism.

The reaction scheme can be written (C=complex between E and S):



The evolution equations for the different species follow the mass action law:

$$\begin{cases} \frac{dS}{dt} = -k_1ES + k_{-1}C \\ \frac{dE}{dt} = -k_1ES + k_{-1}C + k_2C \\ \frac{dC}{dt} = k_1ES - k_{-1}C - k_2C \\ \frac{dP}{dt} = k_2C \end{cases} \quad (38)$$

In their original analysis, Michaelis and Menten assumed that the substrate S is in instantaneous equilibrium with the complex C, i.e.

$$k_1, k_{-1} \gg k_2 \quad (39)$$

Thus

$$k_1ES = k_{-1}C \quad (40)$$

Since  $E_T = E + C$ , we find that:

$$C = \frac{E_T S}{\frac{k_{-1}}{k_1} + S} \quad (41)$$

Hence, the product P of the reaction is produced at a rate

$$v = \frac{dP}{dt} = k_2C = V_{max} \frac{S}{K_S + S} \quad (42)$$

where

$$V_{max} = k_2E_T \text{ and } K_S = \frac{k_{-1}}{k_1}$$

## 2.3 Quasi-steady state assumption: Briggs-Haldane equation

Based on the same reaction mechanism (fig. 7 and eqs. (38)), Briggs and Haldane (1925) suggested an alternative hypothesis: if the enzyme is present in “catalytic” amounts (i.e.  $E \ll S$ ), then, very shortly after mixing E and S, a steady state is established in which the concentration of ES (variable  $C$  in eqs. 38) remains essentially constant with time (see figure 8):

$$\frac{dC}{dt} = \frac{dE}{dt} = 0 \quad (43)$$

We define  $E_{tot}$  the total concentration of enzyme:  $E_{tot} = E + C = \text{constant}$ .

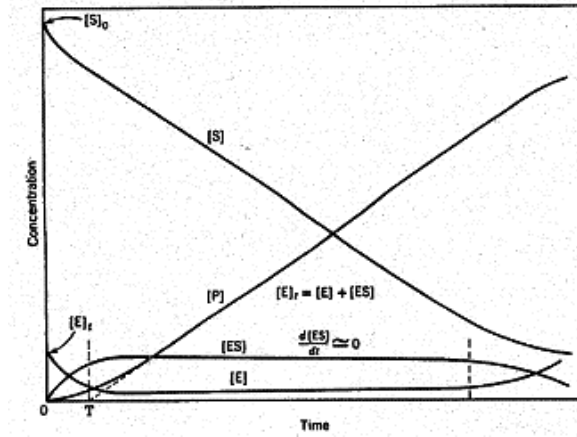


Figure 8: Evolution of the concentration in an enzyme-catalyzed reaction.

This hypothesis is the **quasi-steady state approximation** (see appendix for the detailed demonstration). This assumption implies (see the second equation of eqs. (38) with the condition given by eq. (43)) that:

$$k_1ES - k_{-1}C - k_2C = 0 \quad (44)$$

From this equation, with  $E_{tot} = E + C$ , we can extract  $C$ :

$$C = \frac{k_1E_{tot}S}{k_1S + (k_{-1} + k_2)} = \frac{E_{tot}S}{S + \frac{(k_{-1} + k_2)}{k_1}} \quad (45)$$

When we replace this expression for  $C$  in the rate of appearance of  $P$ , we obtain:

$$v = \frac{dP}{dt} = k_2C = \frac{k_2E_{tot}S}{S + \frac{(k_{-1} + k_2)}{k_1}} \quad (46)$$

which is usually written as:

$$v = V_{max} \frac{S}{S + K_M} \quad (47)$$

where

$$K_M = \frac{(k_{-1} + k_2)}{k_1} \text{ and } V_{max} = k_2E_{tot}$$

The rate is thus similar than in the case of the equilibrium hypothesis (Michaelis-Menten equation); only  $K_M$  has a slightly different meaning. We see that when  $k_1, k_{-1} \gg k_2$ , we have  $K_M \rightarrow K_S$ . Note that  $K_M$  is usually called the Michaelis-Menten constant, although the exact meaning of this constant is rarely specified.

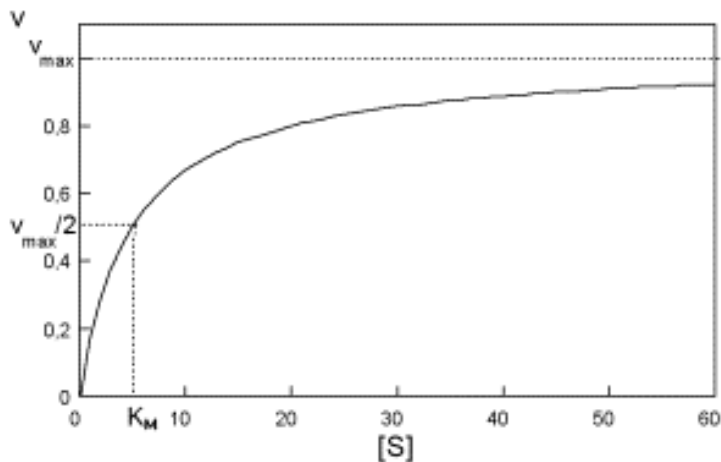


Figure 9: Michaelis-Menten kinetics.

Rewritten in the following manner, equation (47) gives a straight line, which is useful to determine the parameters  $K_M$  and  $V_{max}$  (Lineweaver-Burk representation):

$$\frac{1}{v} = \frac{1}{V_{max}} + \frac{K_M}{V_{max}} \frac{1}{S} \quad (48)$$

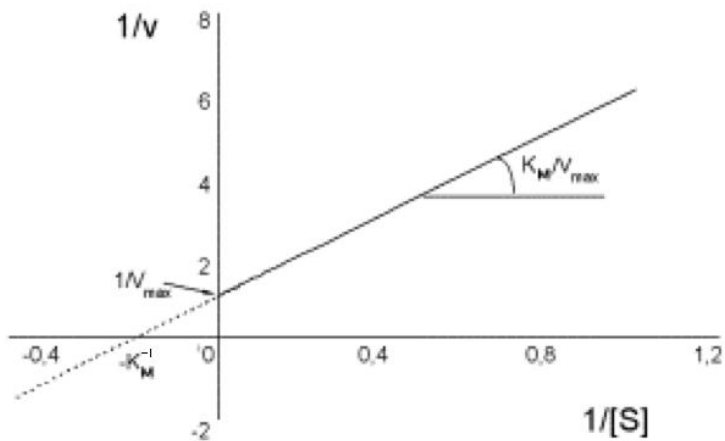


Figure 10: Michaelis-Menten kinetics (Lineweaver-Burk plot).

## 2.4 Inhibition

### Competitive inhibition

In the case of a competitive inhibition, the inhibitor is in competition with the substrate for the active site of the enzyme: either one or the other can bind the enzyme, but not both at the same time.

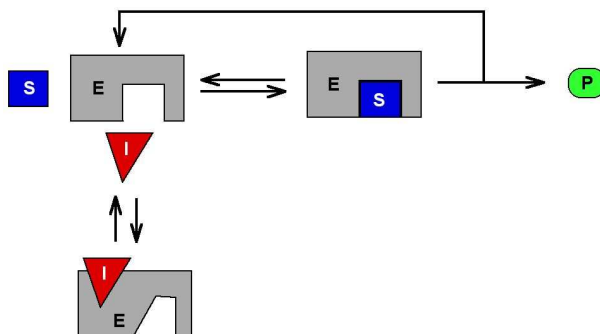
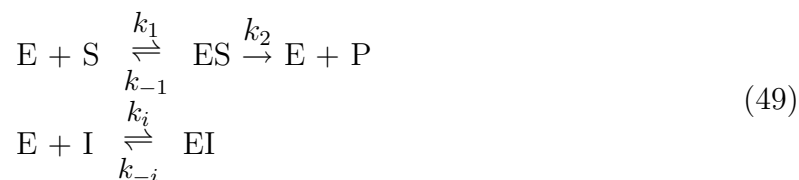


Figure 11: Competitive inhibition: mechanism.

The reaction scheme is:



The rate of appearance of P depends on the concentration of the inhibitor I in the following manner:

$$v = V_{max} \frac{S}{K_M \left(1 + \frac{I}{K_I}\right) + S}
 \tag{50}$$

where  $K_I$  is the equilibrium constant of the EI complex formation:  $K_I = k_{-i}/k_i$ .

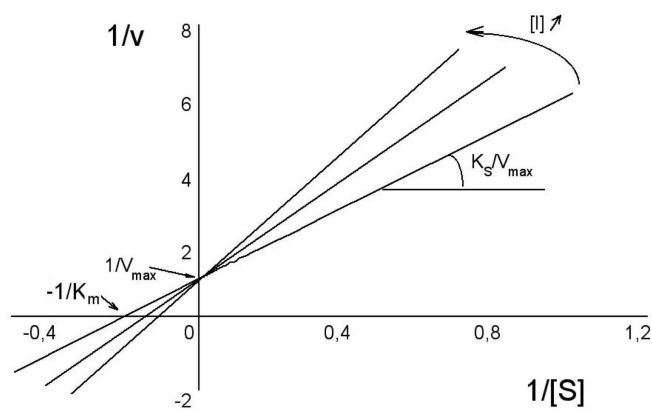


Figure 12: Competitive inhibition.

## Uncompetitive inhibition

In the case of an uncompetitive inhibition, the inhibitor is not in competition with the substrate for the active site of the enzyme. It binds only the substrate-enzyme complex. The substrate facilitates the binding of the inhibitor to the enzyme.

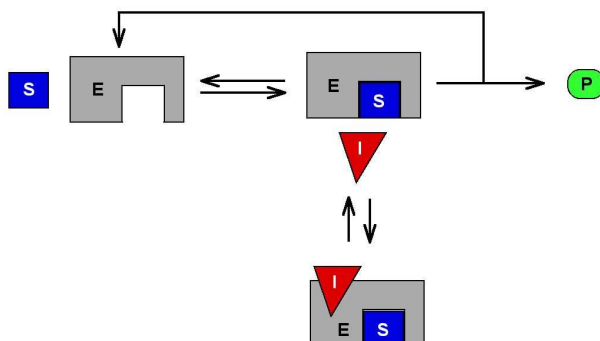
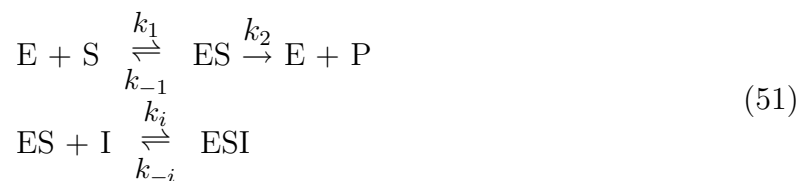


Figure 13: Anti-competitive inhibition: mechanism.

The reaction scheme is:



The rate of appearance of P depends on the concentration of the inhibitor I in the following manner:

$$v = V_{max} \frac{\frac{S}{K_M}}{\left(1 + \frac{I}{K_I}\right) + \frac{S}{K_M}}
 \tag{52}$$

where  $K_I = k_{-i}/k_i$ .

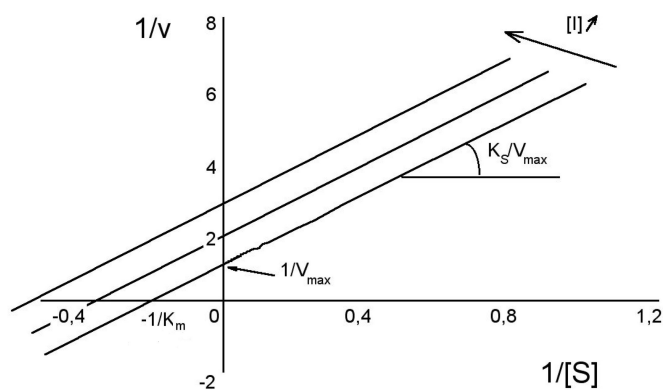


Figure 14: Anti-competitive inhibition.

## Non-competitive inhibition

In the case of a non-competitive inhibition (also said mixed inhibition), both types of inhibition are present: the inhibitor can bind either the free enzyme or the enzyme-substrate complex.

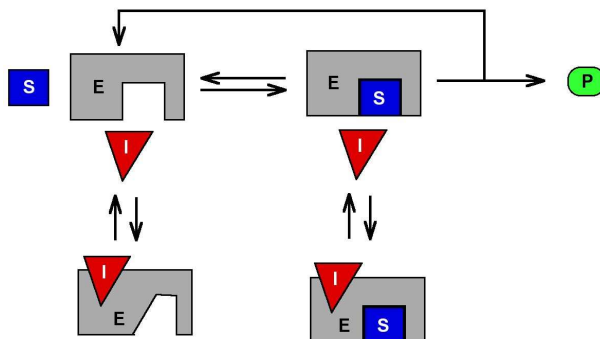
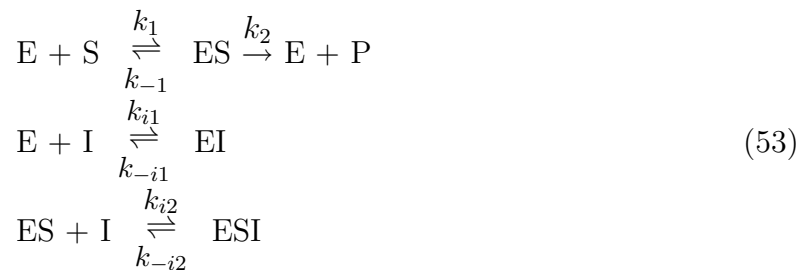


Figure 15: Non-competitive inhibition: mechanism.

The reaction scheme is:



The rate of appearance of P depends on the concentration of the inhibitor I in the following manner:

$$v = \frac{V_{max}}{\left(1 + \frac{I}{K_{I1}}\right)} \frac{S}{\frac{K_M \left(1 + \frac{I}{K_{I1}}\right)}{\left(1 + \frac{I}{K_{I2}}\right)} + S} \tag{54}$$

where  $K_{I1} = k_{-i1}/k_{i1}$  and  $K_{I2} = k_{-i2}/k_{i2}$ .

If  $K_{I1} = K_{I2} = K_I$  (i.e. if the affinity of the inhibitor the enzyme is independent on the binding of the substrate), eq. (54) can be reduced to:

$$v = \frac{V_{max}}{\left(1 + \frac{I}{K_I}\right)} \frac{S}{K_M + S} \tag{55}$$



## 2.5 Activation

Some enzymes need to be activated before to be bound to the substrate (case of essential activation).

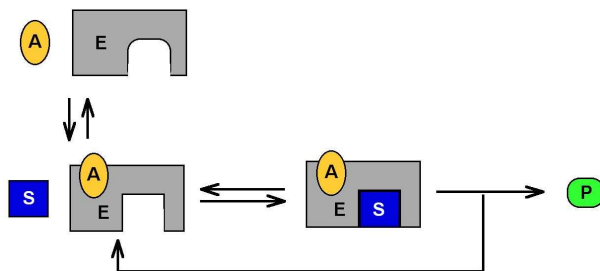
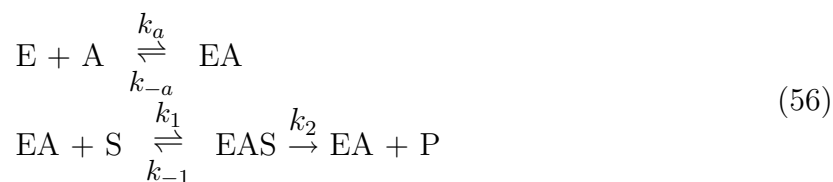


Figure 16: Activation: mechanism.

The reaction scheme is:



The rate of appearance of P depends on the concentration of the activator A in the following manner:

$$v = \frac{V_{max}S}{K_M \left(1 + \frac{K_A}{A}\right) + S} \tag{57}$$

where  $K_A = k_{-a}/k_a$ .

**Remark:** Here it was the case of an essential activation. If  $A = 0$  (no activator), the reaction does not take place. There are also cases where the activator is not essential: the reaction occurs even in absence of the activator A, but at a lower speed. In other cases, it is the substrate (and not the enzyme as considered here above) that need to be activated before being bound to the substrate.

## 2.6 Two-substrate enzyme kinetics

In all the examples treated above, we considered reactions of a single substrate and a single product. Actually such reactions are rather rare in biochemistry. Strictly speaking, they are confined to isomerizations, such as the interconversion of glucose-1-phosphate and glucose-6-phosphate, catalyzed by phosphoglucumutase (Cornish-Bowden, 1995). Nevertheless, these developments of enzyme kinetics are used to describe and to model a large range of biochemical reactions. Many enzymes can be treated as single-substrate enzymes because the second substrate is usually present in large excess, so that its concentration can be treated as a constant ( $\text{H}_2\text{O}$ , NAD, ATP, etc). However, there is a number of cases where the two substrates are in comparable amount. For these cases, it is important to consider explicitly the binding of each substrate to the enzyme. Various mechanisms may be assumed. We present here the mechanism based on the formation of a ternary complex. Other mechanisms can be found in textbooks (e.g. Cornish-Bowden, 1995).

Consider the following reaction, catalyzed by enzyme E:



A and B are two substrates. P and Q are the products. We assume that (1) A and B bind independently two different sites of the enzyme, (2) a ternary complex EAB is formed, and (3) once P and Q are formed they are released and the reverse reaction does not take place. This model is schematized in Fig. 17.

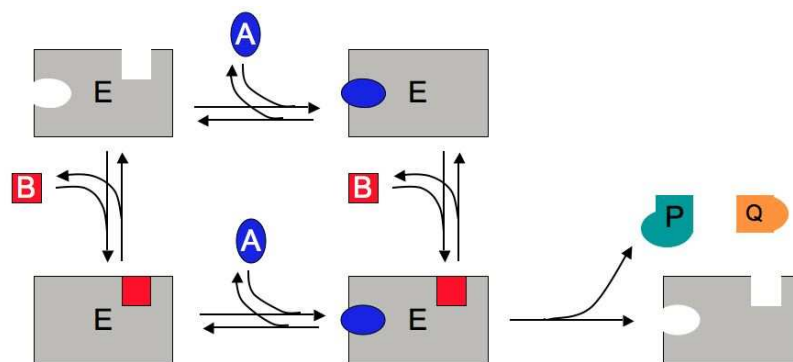
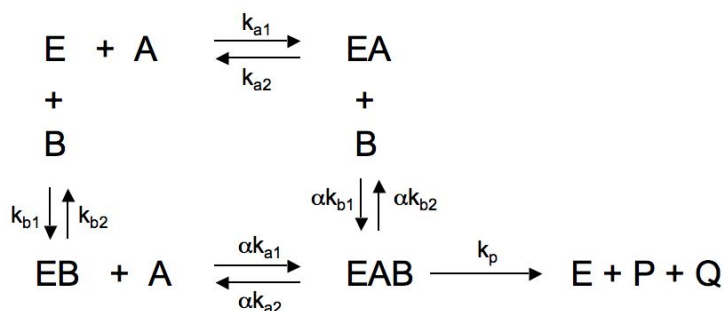


Figure 17: Two substrates enzyme kinetics: mechanism with ternary complex

The kinetic parameters are defined as follows:



The kinetic rates for the substrates A and B are given by:

$$\begin{aligned}\frac{dA}{dt} &= -k_{a1}.E.A + k_{a2}EA - \alpha k_{a1}.A.EB + \alpha k_{a2}.EAB \\ \frac{dB}{dt} &= -k_{b1}.E.B + k_{b2}EB - \alpha k_{b1}.B.EA + \alpha k_{b2}.EAB\end{aligned}\quad (59)$$

We assume that the total concentration of the enzyme is constant:

$$E_T = E + EA + EB + EAB = \text{const} \quad (60)$$

As previously, we will show that under the QSSA hypothesis, we can simplify the kinetic equations. The QSSA assumes that the (reversible) binding of A and B to the enzyme is fast compared to the conversion of A and B into the products and hence the binding/unbinding reactions can be set at the steady state:

$$\begin{aligned}k_{a1}.E.A &= k_{a2}EA \\ \alpha k_{a1}.A.EB &= \alpha k_{a2}.EAB \\ k_{b1}.E.B &= k_{b2}EB \\ \alpha k_{b1}.B.EA &= \alpha k_{b2}.EAB\end{aligned}\quad (61)$$

From Eqs. (61), we find:

$$\begin{aligned}EA &= \frac{k_{a1}}{k_{a2}}.E.A \\ EB &= \frac{k_{b1}}{k_{b2}}.E.B\end{aligned}\quad (62)$$

We can then replace  $EA$  and  $EB$  in Eq. (60):

$$E_T = E + \frac{k_{a1}}{k_{a2}}.E.A + \frac{k_{b1}}{k_{b2}}.E.B + EAB \quad (63)$$

and express  $EAB$  as a function of  $A$  and  $B$ :

$$\begin{aligned}EAB &= \frac{k_{a1} k_{b1}}{k_{a2} k_{b2}} \left( \frac{E_T - EAB}{1 + \frac{k_{a1}}{k_{a2}}A + \frac{k_{b1}}{k_{b2}}B} \right) A.B \\ &= K_a K_b \left( \frac{E_T - EAB}{1 + K_a A + K_b B} \right) AB \\ &= \frac{K_a \cdot K_b \cdot E_T \cdot A \cdot B}{1 + K_a + K_b B} \\ &= \frac{K_a K_b \cdot A \cdot B}{1 + \frac{K_a A K_b B}{1 + K_a A K_b B}} \\ &= \frac{K_a K_b B E_T A B}{1 + K_a \cdot A + K_b \cdot B + K_a K_b \cdot A \cdot B} \\ &= \frac{E_T A B}{\frac{1}{K_a K_b} + \frac{A}{K_b} + \frac{B}{K_a} + A \cdot B}\end{aligned}\quad (64)$$

The rate of production of the product P and Q is thus given by:

$$v = \frac{dP}{dt} = k_p \cdot EAB = k_p \frac{E_T AB}{\frac{1}{K_a K_b} + \frac{A}{K_b} + \frac{B}{K_a} + A \cdot B} \quad (65)$$

or, defining  $v_{max}$  as  $k_p E_T$

$$v = v_{max} \frac{AB}{\frac{1}{K_a K_b} + \frac{A}{K_b} + \frac{B}{K_a} + A \cdot B} \quad (66)$$

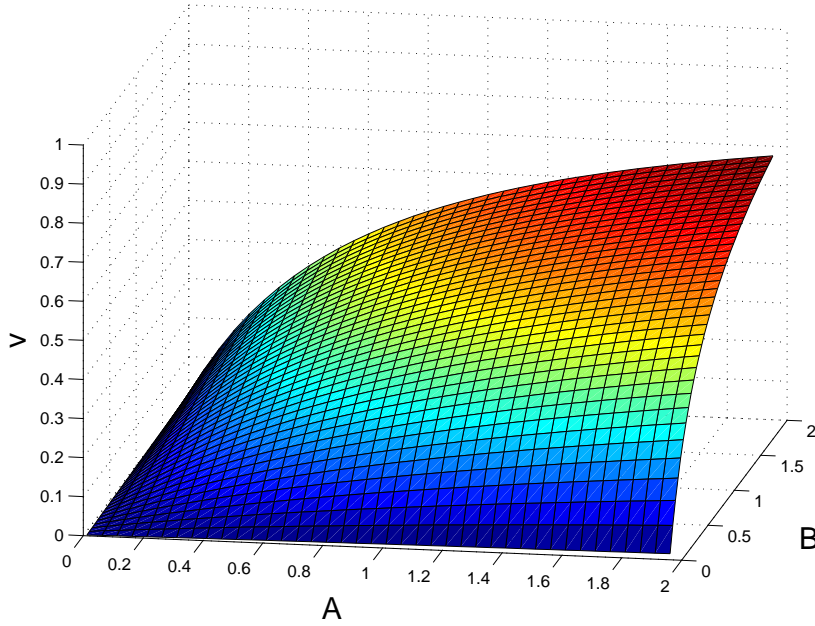


Figure 18: Two substrates kinetics

Note that if  $B$  is constant, the equation becomes

$$v = v'_{max} \frac{A}{K' + A} \quad (67)$$

where

$$v'_{max} = \frac{v_{max} B}{\frac{1}{K_b} + B} \text{ and } K' = \frac{\frac{1}{K_a K_b} + \frac{B}{K_a}}{\frac{1}{K_b} + B} \quad (68)$$

## 2.7 Cooperativity: Hill function

Some enzymes have several active sites. The binding of a molecule of substrate to one site may or not influence the binding of another molecule of substrate to the second site. The two sites are independent in the first case, while they are dependent (cooperative) in the second case. We discuss here both cases. Then we generalised to the case of an enzyme having  $n$  cooperative binding sites.

### Two independent active sites

We first discuss the case of an enzyme with two independent binding sites.

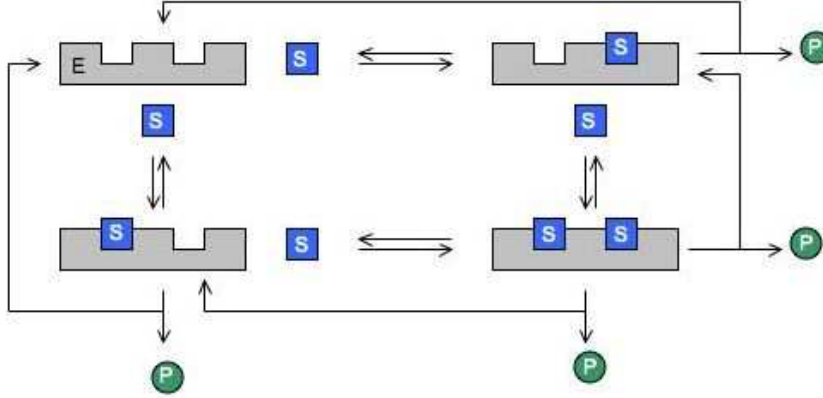
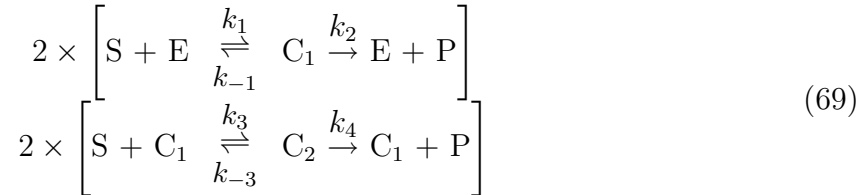


Figure 19: Enzyme with two binding sites: mechanism.

The reaction scheme is as follows:



We define

$$E_T = E + 2C_1 + C_2 \tag{70}$$

The rate of apparition of P is given by:

$$v = 2k_2C_1 + 2k_4C_2 \tag{71}$$

NB: In the rhs, the first “2” stands because there is 2 forms of  $C_1$ , while the second “2” stands for the fact that there are 2 catalytic sites on  $C_2$ .

The evolution equations are:

$$\begin{cases} \frac{dS}{dt} = 2(-k_1SE + k_{-1}C_1 - k_3SC_1 + k_{-3}C_2) \\ \frac{dC_1}{dt} = 2(k_1SE - (k_{-1} + k_2)C_1 - k_3SC_1 + (k_{-3} + k_4)C_2) \\ \frac{dC_2}{dt} = 2(k_3SC_1 - (k_{-3} + k_4)C_2) \end{cases} \tag{72}$$

The quasi steady state approximation allows:

$$\frac{dC_1}{dt} = \frac{dC_2}{dt} = 0 \quad (73)$$

Defining

$$K_1 = \frac{k_{-1} + k_2}{k_1} \text{ and } K_2 = \frac{k_{-3} + k_4}{k_3} \quad (74)$$

we find:

$$C_1 = \frac{SE}{K_1} \text{ and } C_2 = \frac{SC_1}{K_2} = \frac{S^2E}{K_1K_2} \quad (75)$$

The two binding sites are assumed to be independent. This means that

$$\begin{aligned} k_1 &= k_3 = k_+ \\ k_{-1} &= k_{-3} = k_- \\ k_2 &= k_4 = k_p \end{aligned} \quad (76)$$

Combining eq. (71) and (70), with (76), we have

$$\frac{v}{E_T} = 2 \frac{k_p C_1 + k_p C_2}{E + 2C_1 + C_2} \quad (77)$$

Replacing  $C_1$  and  $C_2$  by their expressions (eqs. 75), we get

$$\frac{v}{E_T} = \frac{2 \left( \frac{SE}{K_1} + \frac{S^2E}{K_1K_2} \right)}{E + 2 \frac{SE}{K_1} + \frac{S^2E}{K_1K_2}} \quad (78)$$

Noting

$$K = K_1 = K_2 = \frac{k_- + k_p}{k_+} \quad (79)$$

we find

$$\begin{aligned} v &= 2k_p E_T \frac{(K+S)S}{K^2 + 2KS + S^2} \\ v &= 2k_p E_T \frac{(K+S)S}{(K+S)^2} \\ v &= 2k_p E_T \frac{S}{(K+S)} \end{aligned} \quad (80)$$

Therefore,

$$v = V_{max} \frac{S}{(K+S)} \quad (81)$$

where

$$V_{max} = 2k_p E_T \text{ and } K = \frac{k_- + k_p}{k_+}$$

The rate has a similar form as in the case of Michaelis-Menten. The maximum rate is simply two times the rate of a one binding site enzyme.

## Two cooperative active sites

The binding of the substrate can sometimes be cooperative, which means that the binding of one molecule of substrate favors the binding of other molecules of substrate to the neighbour binding sites.

This is the case if, in the reaction scheme (69),

$$k_3 \gg k_1 \quad (82)$$

Then we have

$$K_2 = \alpha K_1 \quad (83)$$

with

$$\alpha \ll 1$$

and

$$C_1 = \frac{SE}{K_1} \ll C_2 = \frac{1}{\alpha} \frac{S^2 E}{K_1^2} \quad (84)$$

Thus

$$v = \frac{2k_p E_T \left( \frac{S}{K_1} + \frac{S^2}{\alpha K_1^2} \right)}{1 + 2\frac{S_1}{K_1} + \frac{S^2}{\alpha K_1^2}} \quad (85)$$

For  $S \simeq K_1$  we find

$$\begin{aligned} v &\simeq \frac{V_{max} \frac{S^2}{\alpha K_1^2}}{1 + \frac{S^2}{\alpha K_1^2}} \\ v &\simeq \frac{V_{max} S^2}{K + S^2} \end{aligned} \quad (86)$$

where

$$K = \alpha K_1^2 \quad (87)$$

We see here that in the case of cooperative binding sites, the rate does not follow a Michaelian function anymore. This function, called Hill function, has a sigmoidal shape.

$$v = V_{max} \frac{S^2}{K + S^2} \quad (88)$$

where

$$K = \alpha K_1^2$$

### Generalisation: $n$ cooperative active sites

The reaction scheme for an enzyme with 4 binding sites can be represented as follows, where  $K_i$  denotes the equilibrium (dissociation) constant of the  $i$ th step of binding:  $K_i = \frac{\overleftarrow{k}_i}{\overrightarrow{k}_i}$ . Cooperativity implies that  $K_1 > K_2 > K_3 > K_4$ . In other words, the more S molecules are already bound, the easier the binding of additional S molecules becomes.

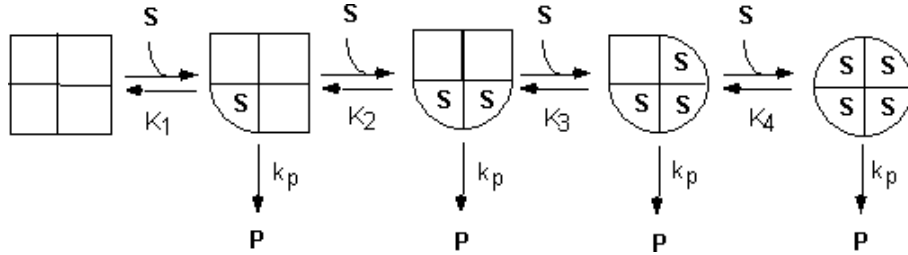


Figure 20: Cooperativity: mechanism.

If we assume that the binding of substrate is cooperative and that all forms of the enzyme-substrate complex (ES1, ES2, ES3 and ES4) are able to transform S into P, the rate of apparition of P is:

$$v = V_{max} \frac{S^n}{K^n + S^n} \quad (89)$$

where  $V_{max}$  is function of  $k_P$  and  $E_{tot}$  (with  $E_{tot} = E + ES1 + ES2 + ES3 + ES4$ ):

$$V_{max} = nk_P E_{tot}$$

and  $K$  is function of the  $K_i$ . If  $K_i = \alpha_i K_{i-1}$ ,

$$K^n = K_1^n \prod_{i=1}^n \alpha_i^{n-i} = K_1^n (\alpha_1^{n-1} \alpha_2^{n-2} \dots) \quad (90)$$

The curve defined by eq. (89) has a sigmoidal shape, with  $v = V_{max}/2$  at  $S = K$ .

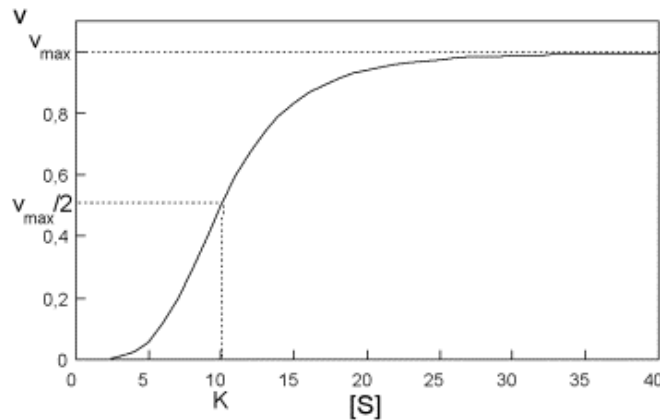


Figure 21: Hill kinetics.



**Remark:** It is important to stress that the Hill coefficient  $n$  is not equal to the number of binding sites. In fact,  $n$  tends to the number of binding sites when the cooperativity is very strong. In practice, however, the cooperativity is never infinite and  $n$  is generally less than the number of binding sites (and can take non-integer values).

Equation (22) can be transformed to show a linear relation, as in the Lineweaver-Burk representation of Michaelis-Menten equation:

$$\frac{v}{V_{max}} = \frac{S^n}{K^n + S^n} \quad (91)$$

$$S^n \frac{V_{max} - v}{v} = K^n \quad (92)$$

$$\log \left( \frac{v}{V_{max} - v} \right) = n \log S - n \log K \quad (93)$$

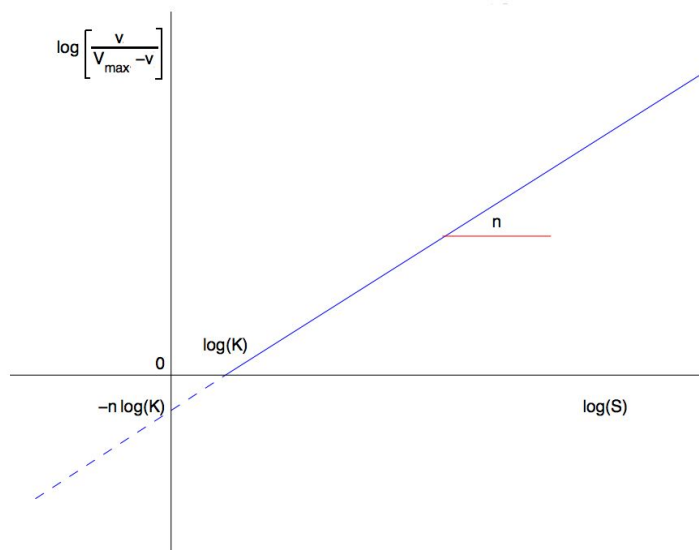


Figure 22: Hill kinetics.

## 2.8 Allosteric model

Monod, Changeux and Jacob (1963) studied many examples of cooperative and allosteric phenomena, and concluded that they were closely related and that conformational flexibility probably accounted for both. Subsequently Monod, Wyman and Changeux (1965) proposed a general model to explain both phenomena within a simple set of postulates. The model is often referred to as the allosteric model.

The allosteric model starts from the observation that each molecule of a typical cooperative protein contains several subunits. We will denote by  $n$  the number of subunits (Fig. 23A).

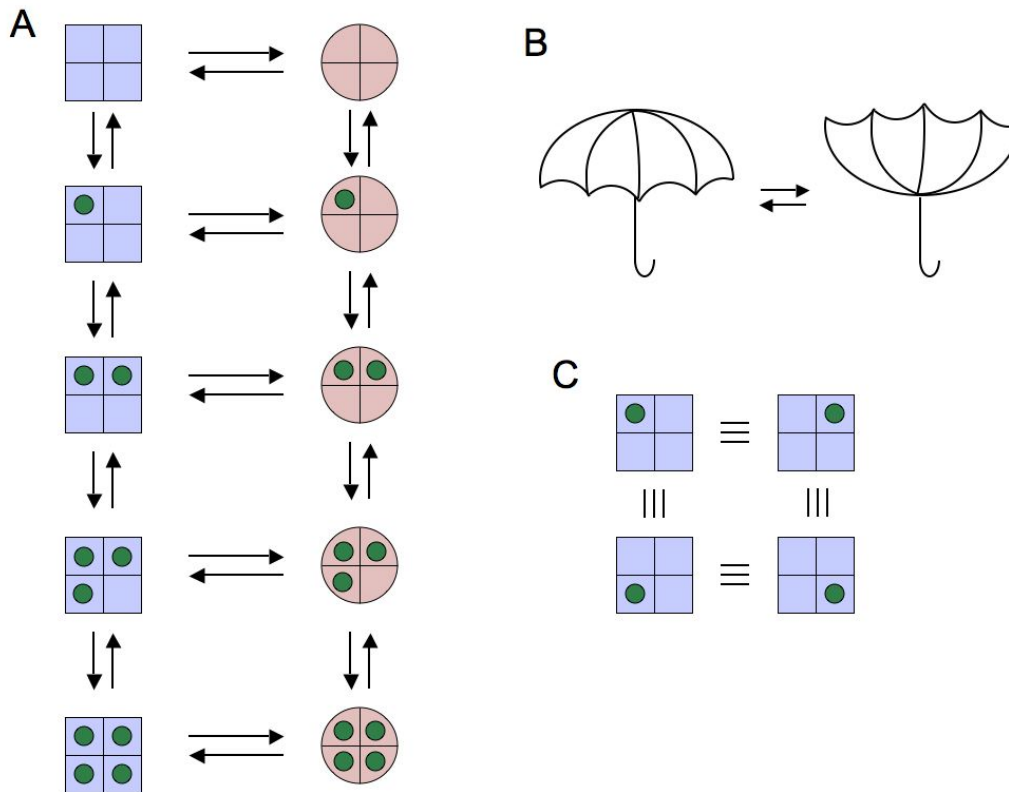


Figure 23: Allosteric model.

The model then relies on the following assumptions:

- Each subunit can exist in two different conformations, designed R and T. These labels originally stood for *relaxed* and *tense*, from the idea that the protein had to relax in order to bind substrate.
- All subunits of the enzyme must be in the same conformation at any time (*umbrella effect*, Fig. 23B). Hence, for a dimeric protein the conformational states  $R_2$  and  $T_2$  are the only ones permitted, the mixed conformation  $RT$  being forbidden (this condition becomes much more restrictive when the enzyme counts more than 2 subunits (e.g. for  $n = 4$  the allowed states are  $R_4$  and  $T_4$ , while  $R_3T$ ,  $R_2T_2$ ,  $RT_3$  are all forbidden).

- The two states of the protein are in equilibrium, with an equilibrium (allosteric) constant  $L=[R_2]/[T_2]$ .
- A ligand (substrate)  $A$  can bind to a subunit in either conformation, but the dissociation constant are different:  $K_R = [R][A]/[RA]$  for each  $R$  subunit;  $K_T = [T][A]/[TA]$  for each  $T$  subunit. The ratio  $c = K_R/K_T < 1$ . In other words the affinity of the substrate is not the same for the two forms.

We describe here the derivation of the equations for the case of an enzyme with 2 subunits. We then discuss the generalization to the case of  $n$  subunits.

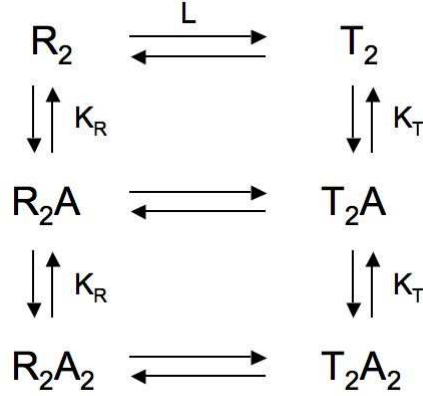


Figure 24: Scheme of the allosteric model.

The assumptions listed above imply the set of equilibria between the various states shown in Fig. 24 ( $R_2 \rightleftharpoons T_2$ ,  $R_2 + A \rightleftharpoons R_2A$ ,  $R_2A + A \rightleftharpoons R_2A_2$ , etc.) and the concentrations of the 6 forms of the protein are related by the following expressions:

$$\begin{aligned}
 [R_2A] &= 2[R_2][A]/K_R \\
 [R_2A_2] &= \frac{1}{2}[R_2A][A]/K_R = [R_2][A]^2/K_R^2 \\
 [T_2] &= L[R_2] \\
 [T_2A] &= 2[T_2][A]/K_T = 2L[R_2][A]/K_T \\
 [T_2A_2] &= \frac{1}{2}[T_2A][A]/K_T = L[R_2][A]^2/K_T^2
 \end{aligned} \tag{94}$$

In each equation the factor 2, 1/2 or 1 results from the fact that the dissociation constants are defined in terms of individual sites but the expression are written for the complete molecules. For example  $K_R = [R][A]/[RA] = 2[R_2][A]/[R_2A]$ , because there are two vacant sites in each  $R_2$  molecule and one occupied site in each  $R_2A$  molecule (see also Fig. 23C).

The fractional saturation  $\Phi$  is defined as the fraction of sites occupied by the ligand:

$$\begin{aligned}
 \Phi &= \frac{\text{number of sites occupied by the ligand}}{\text{total number of sites}} \\
 &= \frac{[R_2A] + 2[R_2A_2] + [T_2A] + 2[T_2A_2]}{2([R_2] + [R_2A] + [R_2A_2] + [T_2] + [T_2A] + [T_2A_2])}
 \end{aligned} \tag{95}$$

In the numerator the concentration of each molecule is counted according to the number of occupied sites it contains (the empty sites are not counted), but in the denominator, each molecule is counted according to how many sites it contains, whether it is occupied or not.

Substituting the concentrations from Eqs. (94) into Eq. (95), we get:

$$\begin{aligned}\Phi &= \frac{[A]/K_R + [A]^2/K_R^2 + L[A]/K_T + L[A]^2/K_T^2}{1 + 2[A]/K_R + [A]^2/K_R^2 + L + 2L[A]/K_T + L[A]^2/K_T^2} \\ &= \frac{(1 + [A]/K_R)[A]/K_R + L(1 + [A]/K_T)[A]/K_T}{(1 + [A]/K_R)^2 + L(1 + [A]/K_T)^2}\end{aligned}\quad (96)$$

For the general case where the enzyme has  $n$  subunits, Eq. (96) becomes:

$$\Phi = \frac{(1 + [A]/K_R)^{n-1}[A]/K_R + L(1 + [A]/K_T)^{n-1}[A]/K_T}{(1 + [A]/K_R)^n + L(1 + [A]/K_T)^n}\quad (97)$$

The shape of the saturation curve defined by Eqs (97) depends on the values of  $n$ ,  $L$ , and  $K_R/K_T$ , as can be illustrated by assigning some extreme values to these constants.

If  $n = 1$ , i.e. if there is only one binding site per molecule, the equation simplifies to

$$\Phi = \frac{[A]}{K_{RT} + [A]} \quad \text{where } K_{RT} = \frac{1 + L}{1/K_R + L/K_T}\quad (98)$$

is the dissociation constant that takes account for the fact that both R and T forms participate in the binding. The complexity of this dissociation constant does not however alter the fact that it is a constant, and thus no cooperativity is possible if  $n = 1$ .

If  $L = 0$ , the T form of the protein does not exist under any condition, and the factor  $(1 + [A]/K_R)^{n-1}$  cancels between the numerator and the denominator, leaving

$$\Phi = \frac{[A]}{K_R + [A]}\quad (99)$$

which predicts hyperbolic (non-cooperative) binding with dissociation constant  $K_R$ . A similar simplification occurs if  $L$  approaches infinity, i.e. if the R form does not exist. In this case,  $\Phi = [A]/(K_T + [A])$ . It follows that both R and T forms are needed if cooperativity is to be possible.

It is also necessary for the two forms to be functionally different from each other, i.e.  $K_R \neq K_T$ . If  $K_R = K_T$  it is again possible to cancel the common factor  $(1 + [A]/K_R)^{n-1}$ , leaving an hyperbolic expression. This illustrates the reasonable expectation that if the ligand binds equally well to the two states of the enzyme, the relative proportion in which they exist are irrelevant to the binding behaviour.

If  $K_T \gg K_R$ , i.e. if A binds only to the R state, we find:

$$\Phi = \frac{(1 + [A]/K_R)[A]/K_R}{L + (1 + [A]/K_R)^2}\quad (100)$$

When  $[A]$  is sufficiently large, then  $L$  at the denominator becomes negligible and the curve approaches a hyperbola. But when  $[A]$  is small, the constant  $L$  dominates the

denominator and causes  $\Phi$  to rise very slowly from the origin as  $[A]$  increases from zero. In other words, as long as  $L$  is significantly different from zero the curve of  $\Phi$  against  $[A]$  must be sigmoidal.

The curve  $\Phi$ , as defined by Eq. (97) is plotted in Fig. 25 for various parameter values.

If we assume that A is a substrate of the allosteric enzyme, which transforms A into a product P, then the kinetics rate  $v$  of appearance of P can write:

$$v = \frac{d[P]}{dt} = v_{max}\Phi \quad (101)$$

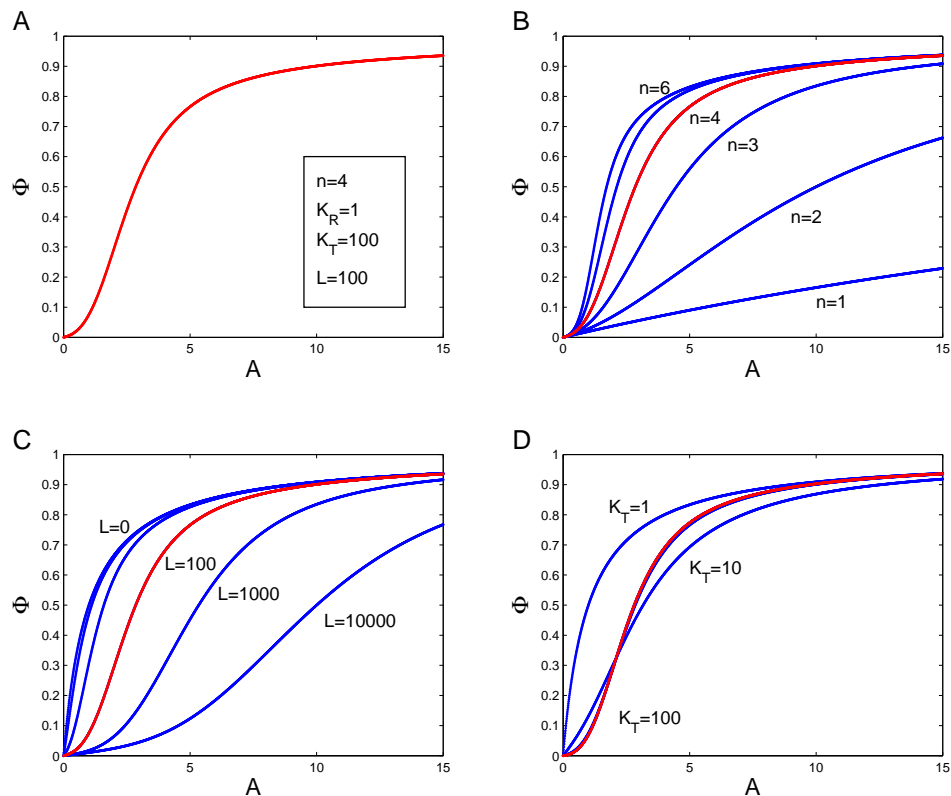


Figure 25: Plot of  $\Phi$  as a function of  $[A]$  for various sets of parameter values. (A) Default parameter values ( $n = 4$ ,  $K_R \gg K_T$ ,  $L \gg 1$ ). (B) Effect of the number of subunits,  $n$ . (C) Effect of the allosteric constant,  $L$ . (D) Effect of the affinity ratio  $c$  (controlled by changing  $K_T$ ,  $K_R$  being fixed).

## 2.9 Zero-order ultrasensitivity

Goldbeter and Koshland showed how ultrasensitivity may arise in a system based on the covalent modification of a protein. They consider a protein that can exist in two forms, e.g. a phosphorylated, active form ( $W^*$ ) and a unphosphorylated, inactive form ( $W$ ), and that the conversion is catalyzed by two different enzymes (e.g. a kinase  $E_1$  and a phosphatase  $E_2$ ). The scheme of such a system is depicted in Fig. 26.

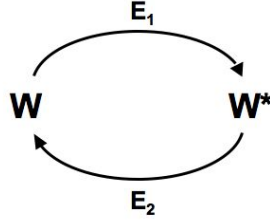
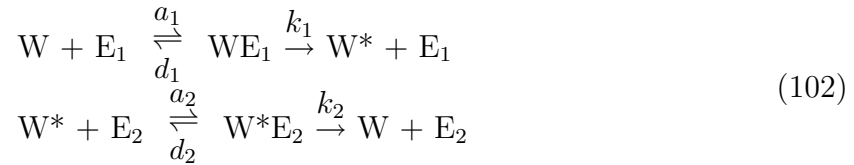


Figure 26: Scheme

Assuming a molecular mechanism similar to the one used to derive the Michaelis-Menten equation, the detailed reaction scheme is as follows:



The corresponding evolution equations are:

$$\begin{aligned}
 \frac{d[W]}{dt} &= -a_1[W][E_1] + d_1[WE_1] + k_2[W^*E_2] \\
 \frac{d[WE_1]}{dt} &= a_1[W][E_1] - (d_1 + k_1)[WE_1] \\
 \frac{d[W^*]}{dt} &= -a_2[W^*][E_2] + d_2[W^*E_2] + k_1[WE_1] \\
 \frac{d[W^*E_2]}{dt} &= a_2[W^*][E_2] - (d_2 + k_2)[W^*E_2]
 \end{aligned} \tag{103}$$

We assume that the total concentration of  $W$ ,  $E_1$ , and  $E_2$  are constant:

$$\begin{aligned}
 W_T &= [W] + [W^*] + [WE_1] + [W^*E_2] \\
 E_{1T} &= [E_1] + [WE_1] \\
 E_{2T} &= [E_2] + [W^*E_2]
 \end{aligned} \tag{104}$$

The steady state can be obtained by solving:

$$\begin{aligned}
 a_1[W][E_1] - d_1[E_1] &= k_1[WE_1] = k_2[W^*E_2] \\
 a_2[W^*E_2] - d_2[E_2] &= k_1[WE_1] = k_2[W^*E_2]
 \end{aligned} \tag{105}$$

Thus, at steady state:

phosphorylation rate = dephosphorylation rate

$$k_1[W E_1] = k_2[W^* E_2] \quad (106)$$

We define the fraction of the active and inactive forms of the protein at steady state:

$$\begin{aligned} W^* &= \frac{[W^*]}{W_T} \\ W &= \frac{[W]}{W_T} \end{aligned} \quad (107)$$

Suppose

$$[W E_1], [W^* E_2] \ll [W], [W^*] \quad (108)$$

when

$$W_T \gg E_{1T}, E_{2T} \quad (109)$$

Then

$$W_T \approx [W] + [W^*] \quad (110)$$

$$\begin{aligned} k_1[W E_1] &= a_1[W][E_1] - d_1[W E_1] \\ (k_1 + d_1)[W E_1] &= a_1[W](E_{1T} - [W E_1]) \\ \left(\frac{k_1 + d_1}{a_1}\right)[W E_1] &= [W]E_{1T} - [W][W E_1] \end{aligned} \quad (111)$$

Thus,

$$[W E_1] = \frac{[W]E_{1T}}{K_{m1} + [W]} \quad (112)$$

with

$$K_{m1} = \left(\frac{k_1 + d_1}{a_1}\right) \quad (113)$$

Similarly, we find:

$$[W^* E_2] = \frac{[W^*]E_{2T}}{K_{m2} + [W^*]} \quad (114)$$

with

$$K_{m2} = \left(\frac{k_2 + d_2}{a_2}\right) \quad (115)$$

We define the maximum rates of  $E_1$  and  $E_2$ :

$$\begin{aligned} v_1 &= k_1 E_{1T} \\ v_2 &= k_2 E_{2T} \end{aligned} \quad (116)$$

Relation (106) thus writes

$$\begin{aligned} k_1[W E_1] &= k_2[W^* E_2] \\ k_1 \frac{[W]E_{1T}}{K_{m1} + [W]} &= k_2 \frac{[W^*]E_{2T}}{K_{m2} + [W^*]} \\ v_1 \frac{[W]}{K_{m1} + [W]} &= v_2 \frac{[W^*]}{K_{m2} + [W^*]} \end{aligned} \quad (117)$$

Defining the molar fractions

$$\begin{aligned} w^* &= \frac{[W^*]}{[W_T]} \\ w &= \frac{[W]}{[W_T]} \\ w + w^* &= 1 \end{aligned} \tag{118}$$

and the normalized Michaelian constants:

$$\begin{aligned} K_1 &= \frac{K_{m1}}{[W_T]} \\ K_2 &= \frac{K_{m2}}{[W_T]} \end{aligned} \tag{119}$$

we obtain

$$\frac{v_1(1 - w^*)}{K_1 + (1 - w^*)} = v_2 \frac{w^*}{K_2 + w^*} \tag{120}$$

or, after rearranging the equation:

$$\frac{v_1}{v_2} = \frac{w^*(K_1 + 1 + w^*)}{(1 - w^*)(K_2 + w^*)} \tag{121}$$

$w^*$  is solution of a second-degree equation:

$$w^* \left( \frac{v_1}{v_2} - 1 \right) - w^* \left[ \left( \frac{v_1}{v_2} - 1 \right) - K_2 \left( \frac{v_1}{v_2} + \frac{K_1}{K_2} \right) \right] - K_2 \left( \frac{v_1}{v_2} \right) \tag{122}$$

Let's call

$$\phi = \left( \frac{v_1}{v_2} - 1 \right) - K_2 \left( \frac{v_1}{v_2} + \frac{K_1}{K_2} \right) \tag{123}$$

Then

$$w^* = \frac{\phi + \left[ \phi^2 + 4 \left( \frac{v_1}{v_2} - 1 \right) K_2 \left( \frac{v_1}{v_2} \right) \right]^{1/2}}{2 \left( \frac{v_1}{v_2} - 1 \right)} \tag{124}$$

In the particular case where  $v_1 = v_2$ , we find

$$\begin{aligned} v_2(1 - w^*)(K_2 + w^*) &= v_2 w^*(K_1 + 1 - w^*) \\ w^* &= \frac{K_2}{K_1 + K_2} \\ w^* &= \frac{1}{1 + \frac{K_1}{K_2}} \end{aligned} \tag{125}$$

More generally,  $v_1 \neq v_2$ , so how does vary  $w^*$  with  $v_1/v_2$ ?



Let's first look at the case  $K_1, K_2 \gg 1$ . In that case, Eq. (120) becomes

$$\frac{v_1 w}{K_1} = \frac{v_2 w^*}{K_2} \quad (126)$$

i.e.

$$w^* = \frac{\frac{v_1}{v_2}}{\frac{K_1}{K_2} + \frac{v_1}{v_2}} \quad (127)$$

In the case where  $K_1, K_2 \ll 1$ , the curve for  $w^*$  (defined by Eq. (124)) takes the form of a sigmoid with a very sharp threshold (ultra-sensitivity) (Fig. 27).

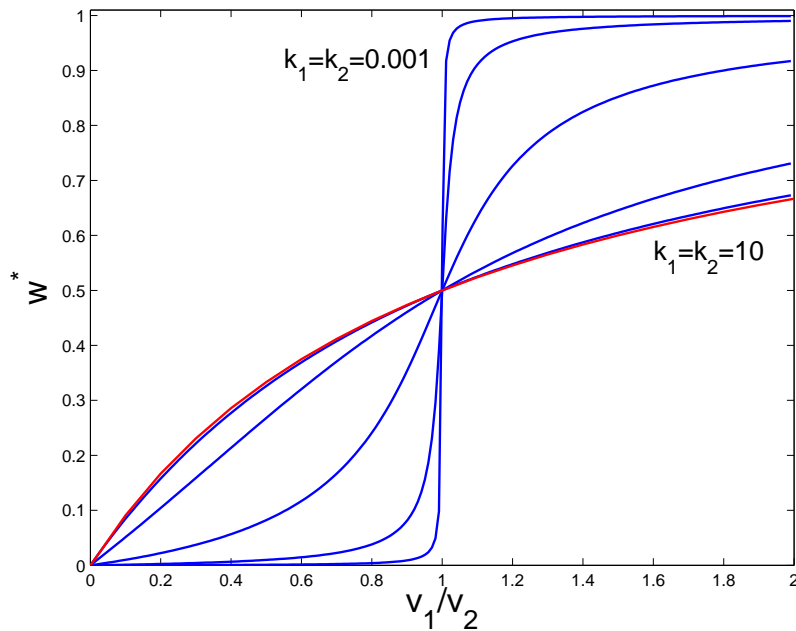


Figure 27: Fraction of active (phosphorylated) protein as a function of the ratio  $v_1/v_2$ . The red curve correspond to the approximation (127) and the blue curves correspond to Eq. (124), for various values of  $K_1 = K_2$ .

## 3 Gene regulation

### 3.1 Transcription, regulation, and transcription factors

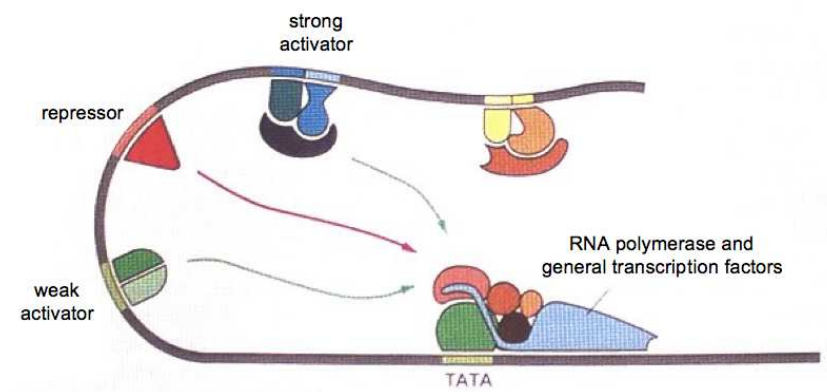
Transcription of a gene is the process by which RNA polymerase produces mRNA (messenger RNA) that corresponds to the gene coding sequence. The mRNA is then translated into a protein, the gene product. The rate at which the gene is transcribed, i.e. the number of mRNA molecules produced per unit time, is controlled by the promoter, a regulatory region of DNA that very often precedes the gene. RNA polymerase binds a specific binding site (DNA sequence) at the promoter, thereby leading to the assembly of a multimolecular transcription machinery.

Whereas RNA polymerase acts on virtually all of the genes, the expression of specific genes is very often regulated by proteins called transcription factors. These transcription factors affect the transcription rate by binding to specific sites in the promoter of the genes. When bound they change the probability per unit time that RNA polymerase binds the promoter and produces an mRNA molecule. Transcription factors can act as activators that increase the transcription rate of a gene, or as repressors that reduce the transcription rate.

In some cases, an activator may even be required for the transcription to occur (case of “essential” activators). The activity of these regulators can also be controlled by complex formation with small molecules (e.g. the inducer of repressor *lacI* in the case of the *lac* operon of *E. coli*) or by formation of homomeric or heteromeric complexes. Competition between activators and inhibitors for a given binding site can also occur, and be crucial for an appropriate gene regulation. Finally, the situation is even more complex if, in a promoter of a given gene, multiple binding sites are present, being specific for one or several regulators, and possibly leading to cooperative binding.

Transcription factors are proteins that are themselves encoded by genes, which possibly are regulated by other transcription factors, which in turn are regulated by other transcription factors, and so on. Such a set of interactions forms a transcriptional network.

In this section, we have selected a few regulatory mechanisms to illustrate how the kinetics of gene regulation can be derived. These schemes are very simplified and, of course, numerous variants and more detailed models can be elaborated.



### 3.2 Case 1: Transcriptional activation.

A regulator (protein X) is synthesized at a rate  $k_s$  and degraded (or consumed in another reaction) at a rate  $k_d$ . This regulator can reversibly bind the binding site D of the gene Y (denoted  $D_0$  if unbound and  $D_1$  if bound). The binding/unbinding rates are denoted by  $k_1$  and  $k_{-1}$ . Only when activated by the regulator X, the transcription of gene Y can start (fig. 28). The transcription is ensured by the RNA polymerase, P. In a second step, Y mRNA is translated into Y protein. The transcription/translation rate is noted  $k_t$ .

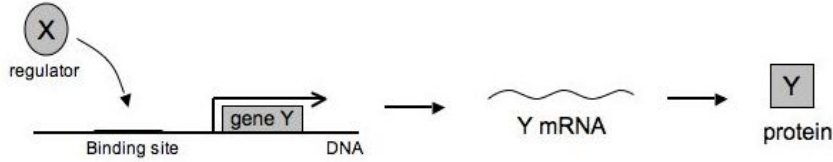
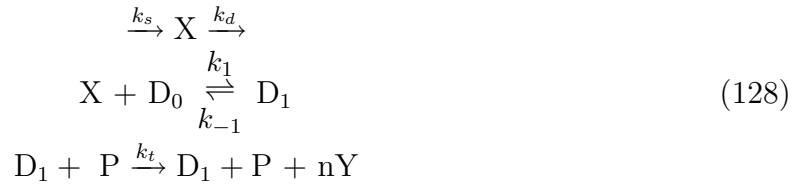


Figure 28: Case 1: A single regulator (X) is required to activate the transcription of a gene (Y). We also assume that the promoter contains a single binding site for protein X.

The reaction scheme assumed for this case is the following:



In this scheme, we can distinguish several time scales (fast vs slow reactions): The binding/unbinding of the regulatory protein to DNA can occur several times by second, while processes like protein synthesis and gene transcription last over several minutes. The protein and mRNA degradation rates are more variable; the life time of these compounds can range from a few seconds to several days.

To simplify, we have condensed the transcription of gene Y and the translation of Y mRNA into a single step.

The kinetics of the above reaction scheme can be written:

$$\begin{aligned}
 \frac{dX}{dt} &= k_s - k_1 D_0 X + k_{-1} D_1 - k_d X \\
 \frac{dD_1}{dt} &= k_1 D_0 X - k_{-1} D_1 \\
 \frac{dY}{dt} &= n k_t P D_1
 \end{aligned} \tag{129}$$

Because of the fast binding-unbinding rate ( $k_1$  and  $k_{-1}$  high), we can apply the quasi-steady state assumption for the binding/unbinding of the regulator X :

$$\frac{dD_1}{dt} = 0 \tag{130}$$

This leads to:

$$k_1 D_0 X = k_{-1} D_1 \quad (131)$$

Defining  $D_T = D_0 + D_1$  the total number of genes or plasmids per unit volume (total concentration of binding sites), we find:

$$k_1 D_T X = (k_1 X + k_{-1}) D_1 \quad (132)$$

$$D_1 = \frac{k_1 D_T X}{k_{-1} + k_1 X} = \frac{D_T X}{K_1 + X} \quad (133)$$

where  $K_1$  is the dissociation constant

$$K_1 = \frac{k_{-1}}{k_1} \quad (134)$$

The larger the dissociation constant, the higher the rate of dissociation of complex  $D_1$ , that is the weaker the binding of X and D.

We find

$$\frac{dY}{dt} = nk_t P \frac{D_T X}{K_1 + X} \quad (135)$$

We can also note that the quasi-steady state assumption leads to:

$$\frac{dX}{dt} = k_s - k_d X \quad (136)$$

and thus the steady state of X depends only on its synthesis and degradation rates:

$$X_s = k_s/k_d \quad (137)$$

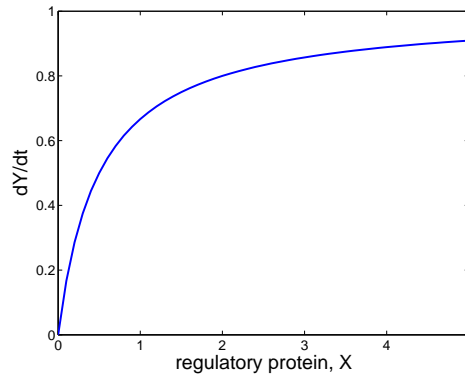


Figure 29: Case 1: The production of Y as a function of the regulatory protein X follows a hyperbolic curve (eq. 135).

**Remark:** Many DNA-transcription factors complex dissociate within less than 1 second, (i.e.  $k_{-1} > 1s^{-1}$ ). Therefore, we can average over times much longer than 1 sec and show, in particular for a single binding site (which is either free or occupied), that  $D_1/D_T$  is the probability that a site D is bound, averaged over many binding and unbinding events. When site D is bound, RNA polymerase can bind the promoter and transcribe the gene.

### 3.3 Case 2: Transcriptional activation with auto-regulation.

In this second study case, we assume that the regulatory protein X regulates the transcription of its own gene, X. In addition, we assume that both  $D_0$  and  $D_1$  can lead to the transcription of the gene X, but with different efficiency (fig. 30).

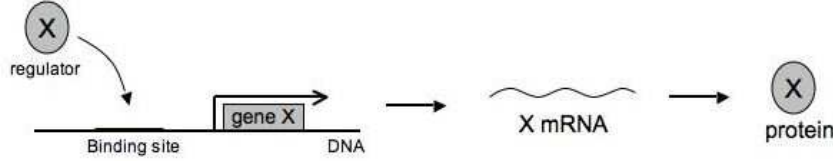
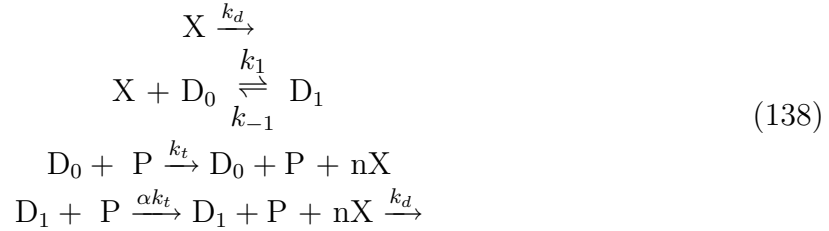


Figure 30: Case 2: A regulatory protein X activates the transcription of its own gene.

The reaction scheme is as followed:



The corresponding kinetics equations are written:

$$\begin{aligned}
 \frac{dX}{dt} &= nk_t P D_0 + n\alpha k_t P D_1 - k_1 D_0 X + k_{-1} D_1 - k_d X \\
 \frac{dD_0}{dt} &= -k_1 X D_0 + k_{-1} D_1 \\
 \frac{dD_1}{dt} &= k_1 X D_0 - k_{-1} D_1 = -\frac{D_0}{dt}
 \end{aligned} \tag{139}$$

The quasi-steady state assumption,  $\frac{dD_0}{dt} = \frac{dD_1}{dt} = 0$ , leads to:

$$k_1 X D_0 = k_{-1} D_1 \tag{140}$$

With the definitions  $K_1 = \frac{k_{-1}}{k_1}$  and  $D_T = D_0 + D_1$  we find:

$$D_1 = \frac{D_T X}{K_1 + X} \tag{141}$$

and the evolution of  $X$  becomes:

$$\frac{dX}{dt} = nk_t P (D_T - D_1) + n\alpha k_t P D_1 - k_d X \tag{142}$$

$$\frac{dX}{dt} = nk_t P D_T \left( 1 + \frac{(\alpha - 1)X}{K_1 + X} \right) - k_d X \quad (143)$$

Depending on the value of  $\alpha$ , the auto-regulation of X leads to either an activation or a repression of its own gene:

- $\alpha = 1$     constitutive expression
- $\alpha > 1$     auto-activation
- $\alpha < 1$     auto-inhibition

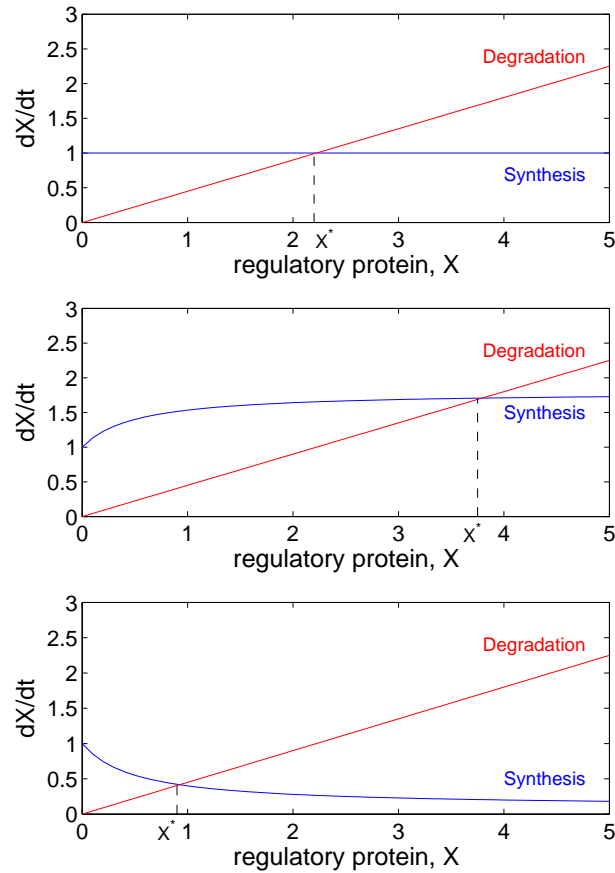


Figure 31: Auto-regulation of the gene X. Upper panel:  $\alpha = 1$  (constitutive expression). Middle panel:  $\alpha > 1$  (activation). Bottom panel:  $\alpha < 1$  (repression).

### 3.4 Case 3: Transcriptional activation with multiple binding sites.

In this third scheme, we assume that there are two binding sites in the promoter of the gene Y and that the regulatory protein can bind these two binding sites, with a different affinity (fig. 32).

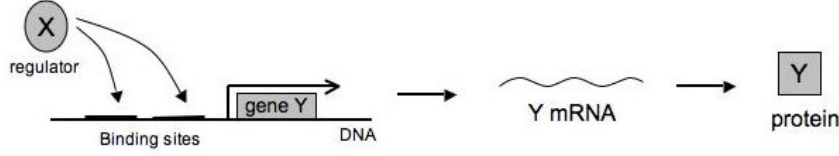


Figure 32: Case 3: A single regulatory protein X binds two binding sites to activate the repression of a gene Y.

The reaction scheme is as followed:



The corresponding kinetics equations are written:

$$\begin{aligned}
 \frac{dX}{dt} &= k_s - k_1 D_0 X + k_{-1} D_1 - \alpha k_1 D_1 X + k_{-1} D_2 - k_d X \\
 \frac{dD_0}{dt} &= -k_1 D_0 X + k_{-1} D_1 \\
 \frac{dD_1}{dt} &= k_1 D_0 X - k_{-1} D_1 - \alpha k_1 D_1 X + k_{-1} D_2 \\
 \frac{dD_2}{dt} &= \alpha k_1 D_1 X - k_{-1} D_2
 \end{aligned} \tag{145}$$

With the quasi-steady state assumption,  $\frac{dD_0}{dt} = \frac{dD_1}{dt} = \frac{dD_2}{dt} = 0$ , we have:

$$\alpha k_1 D_1 X = k_{-1} D_2 \tag{146}$$

With the definition  $K_1 = k_{-1}/k_1$ , we find

$$D_2 = \frac{\alpha}{K_1} D_1 X \text{ and } D_1 = \frac{D_0 X}{K_1} \tag{147}$$

$$D_2 = \frac{\alpha D_0 X^2}{K_1^2} \tag{148}$$

Defining  $D_T$  as previously,  $D_T = D_0 + 2D_1 + D_2$ , we get:

$$D_0 = \frac{D_T}{1 + 2\frac{X}{K_1} + \frac{\alpha X^2}{K_1^2}} \quad (149)$$

If we assume that the gene is transcribed only if the two binding sites are occupied,



then the evolution of protein Y is equal to:

$$\frac{dY}{dt} = nk_t P D_2 = Q D_2 = Q \frac{D_T \alpha X^2 / K_1^2}{1 + 2X/K_1 + \alpha X^2 / K_1^2} \quad (151)$$

where  $Q = nk_t P D_T$  is a constant.

Two situations can be distinguished: either the two binding sites are independent or there are cooperative. If the binding sites are independent and identical, then  $\alpha = 1$  and the above equation can be simplified as:

$$\frac{dY}{dt} = Q \left( \frac{X/K_1}{1 + X/K_1} \right)^2 \quad (152)$$

If we assume cooperativity between the binding sites, then  $\alpha \gg 1$  and we get

$$\frac{dY}{dt} = Q \left( \frac{\alpha X^2 / K_1^2}{1 + 2X/K_1 + \alpha X^2 / K_1^2} \right) \quad (153)$$

which can be approximated by:

$$\frac{dY}{dt} \approx Q \frac{\alpha (X/K_1)^2}{1 + \alpha (X/K_1)^2} \quad (154)$$

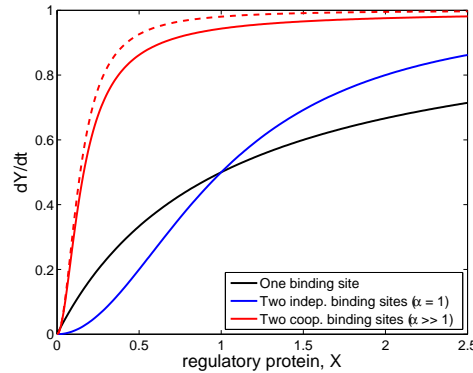


Figure 33: Multiple binding sites. Comparison of the dynamics in the case of a single binding site (eq. (135), black curve), independent (eq. (152), blue curve), and cooperative binding sites (eq. (153), red solid curve, or eq. (154), red dashed curve).



### 3.5 Case 4: Transcriptional activation by a dimeric complex.

In this last study case, we assume that the regulatory protein X, must form a homodimer  $X_2$  before binding the regulatory site.

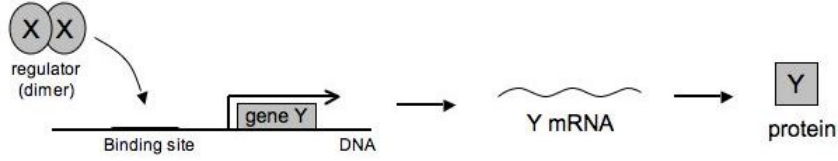
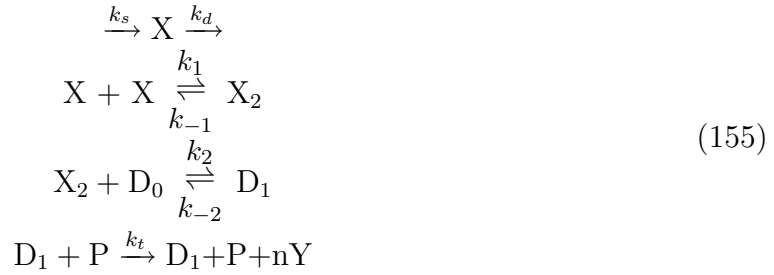


Figure 34: Case 4: The regulatory protein X forms a dimer than can bind the binding site and activate the transcription of gene Y.

The reaction scheme is as followed:



The corresponding kinetics equations are written:

$$\begin{aligned}
 \frac{dX}{dt} &= k_s - k_d X - 2k_1 X^2 + 2k_{-1} X_2 \\
 \frac{dX_2}{dt} &= k_1 X^2 - k_{-1} X_2 - k_2 D_0 X_2 + k_{-2} D_1 \\
 \frac{dD_1}{dt} &= k_2 D_0 X_2 - k_{-2} D_1
 \end{aligned} \tag{156}$$

With the quasi-steady state hypothesis  $\frac{dD_1}{dt} = 0$  and the definition  $D_T = D_0 + D_1$ , we find

$$D_1 = \frac{D_T X_2}{K_2 + X_2} \tag{157}$$

If, in addition, we assume that the dimerisation rate is also fast ( $k_2$  and  $k_{-2}$  high), we can do the hypothesis that

$$\frac{dX_2}{dt} = 0 \tag{158}$$

Then  $X_2$  is given by

$$X_2 = \frac{X^2}{K_1} \tag{159}$$

and

$$D_1 = \frac{D_T X^2 / K_1}{K_2 + X^2 / K_1} = \frac{D_T X^2}{K_1 K_2 + X^2} \quad (160)$$

and the evolution of  $Y$  becomes:

$$\frac{dY}{dt} = nk_t P D_1 = Q D_1 = Q \frac{X^2}{K_1 K_2 + X^2} \quad (161)$$

where  $Q = nk_t P D_T$  is a constant.

Equation (161) has a sigmoidal form, similar to the case of two cooperative binding sites (eq. 153).

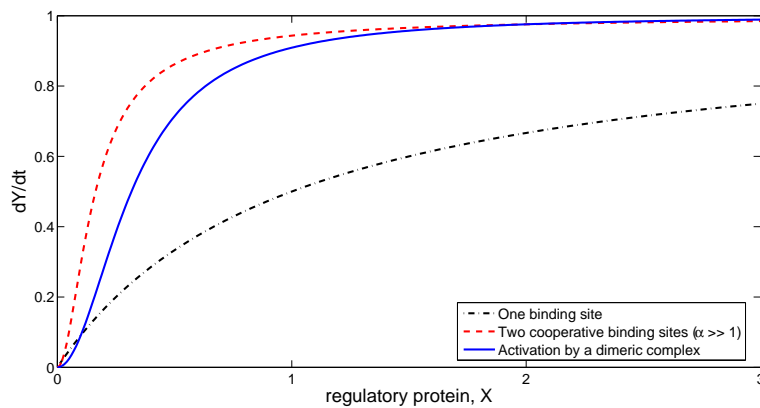


Figure 35: Comparison of cooperative binding sites (eq. 153, red curve) and activation by a homodimeric complex (eq. 161, blue curve).

### 3.6 Case 5: Transcriptional inhibition with an inducer.

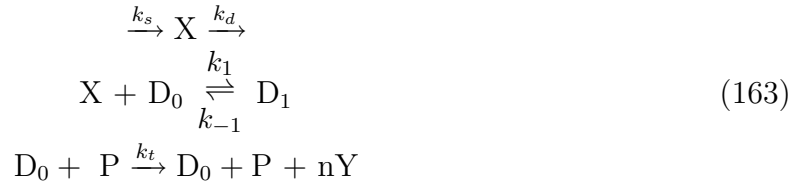
In the case 1, we have seen that the rate of transcription in the case of an activation by an activator X can be expressed as:

$$v \sim \frac{X}{K_1 + X} \quad (162)$$

where  $\frac{X}{K_1 + X}$  can be interpreted as the probability of the promoter to be active (i.e. bound to X).

We can derive the transcription rate in the case where X acts as a repressor in a similar way.

Assuming the following reaction scheme



with the quasi-steady state assumption

$$\frac{dD_0}{dt} = 0 \quad (164)$$

we find

$$v \sim \frac{K_1}{K_1 + X} \quad (165)$$

The term  $\frac{K_1}{K_1 + X}$  is the probability that the promoter is active, i.e. not bound to the repressor X.

Now, let's consider that S can bind X to form a complex [XS]. S is an *inducer* since its binding to X prevents the latter to bind, and thereby to inhibit the promoter.



Assuming that the total concentration of X,  $X_T$ , is constant, the evolution of [XS] is described by

$$\frac{d[XS]}{dt} = k_a X S - k_d [XS] \quad (167)$$

At steady state,  $d[XS]/dt = 0$  and thus  $K_S[XS] = XS$  or  $[XS] = \frac{X_T S}{S + K_S}$  where

$$K_S = \frac{k_d}{k_a}.$$

Thus, the level of active inhibitor is

$$X^* = X_T - \frac{X_T S}{S + K_S} \quad (168)$$

$$= \frac{X_T K_S}{S + K_S} \quad (169)$$

As expected the level of effective inhibitor  $X^*$  decreases when the level of the inducer  $S$  increases.

The transcription rate, in presence of an inhibitor and an inducer, then become:

$$v \sim \frac{K_1}{K_1 + X^*} \quad (170)$$

$$\sim \frac{K_1}{K_1 + \frac{X_T K_S}{S + K_S}} \quad (171)$$

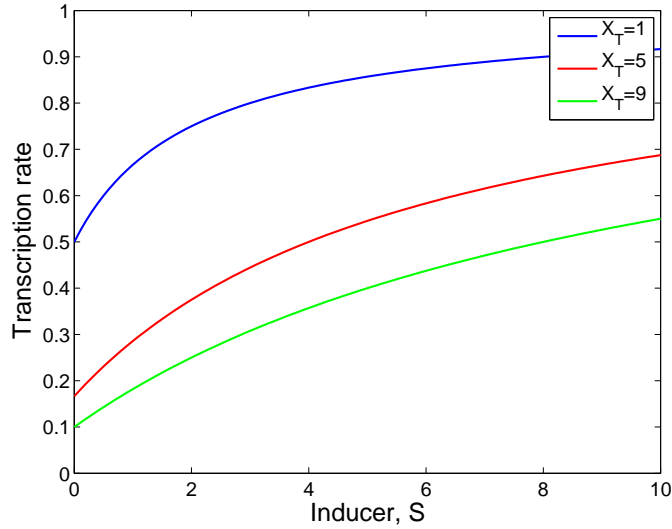


Figure 36: Transcription rate in presence of an inhibitor  $X_T$  and an inducer  $S$  (eq. 171). Note that when there is no inducer ( $S = 0$ ), the transcription still take place, but at a lower rate. Parameter values are:  $v_{max} = 1$ ,  $K_1 = 1$ ,  $K_S = 1$ .

### 3.7 Case 6: Combining transcriptional activation and inhibition.

Many genes are regulated by more than one transcription factor. The combined effects of these regulators can be described by a "multi-dimensional transcription function" (cf Alon's book). As an example let us examine a simple case in which a gene is regulated by a activator  $X$  and an repressor  $Y$ . How can these two regulators work together?

A common situation is that the activator and the repressor bind the promoter independently o two different sites (fig. XX). There are thus four binding states of promoter  $D$ :  $D$ ,  $DX$ ,  $DY$ ,  $DXY$ , where  $DXY$  means that both  $X$  and  $Y$  are bound to the promoter. Transcription occurs mainly from the state  $DX$  in which the activator but not the repressor is bound. In the following we use the variables  $X$  and  $Y$  to denote the active forms of these regulator, i.e.  $X^*$  and  $Y^*$ .

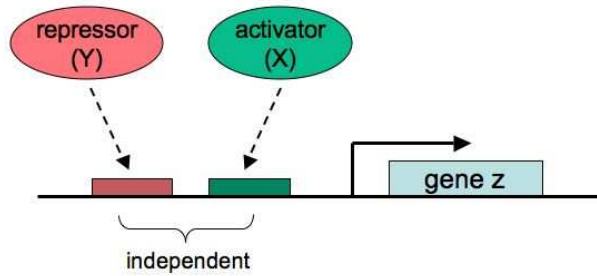


Figure 37: Gene expression can be controlled by several regulator.

The probability that  $X$  is bound is given by the Michaelis-Menten function (see above):

$$P(X \text{ bound}) = \frac{X}{K_1 + X} = \frac{X/K_1}{1 + X/K_1} \quad (172)$$

The probability that  $Y$  is not bound is given by the Michaelis-Menten function (see above):

$$P(Y \text{ not bound}) = 1 - \frac{Y}{K_2 + Y} = \frac{1}{1 + Y/K_2} \quad (173)$$

Since the two binding events are independent, the probability that the promoter  $D$  is bound to  $X$  and not to  $Y$  is given by the product of the two probabilities:

$$\begin{aligned} P(X \text{ bound} \ \& \ Y \text{ not bound}) &= P(X \text{ bound}) \cdot P(Y \text{ not bound}) \\ &= \frac{X/K_1}{1 + X/K_1} \frac{1}{1 + Y/K_2} \\ &= \frac{X/K_1}{1 + X/K_1 + Y/K_2 + XY/K_1K_2} \end{aligned} \quad (174)$$

and the output promoter activity is given by the production rate  $b$  times the probability:

$$v = b \frac{X/K_1}{1 + X/K_1 + Y/K_2 + XY/K_1K_2} \quad (175)$$

This results in an "X AND NOT Y" transcription function.

In many promoters, when the repressor binds, repression is only partial and there is basal transcription (leakage). In such case, the state in which both X and Y bind, DXY also contributes to the transcription rate, with  $b' < b$ , to the promoter activity:

$$v = \frac{bX/K_1 + b'XY/K_1K_2}{1 + X/K_1 + Y/K_2 + XY/K_1K_2} \quad (176)$$

This results in an input function with three plateau levels: zero when  $X = 0$ ,  $b$  when  $X$  is high and  $Y$  low, and  $b'$  when both  $X$  and  $Y$  are high. This continuous input function can be approximated by a logic function:

$$v = \theta(X > K_1)(b(1 - \theta(Y > K_2)) + b'\theta(Y > K_2)) \quad (177)$$

where  $\theta$  is the step function, equal to 0 (if its argument is false) or 1 (if its argument is true).

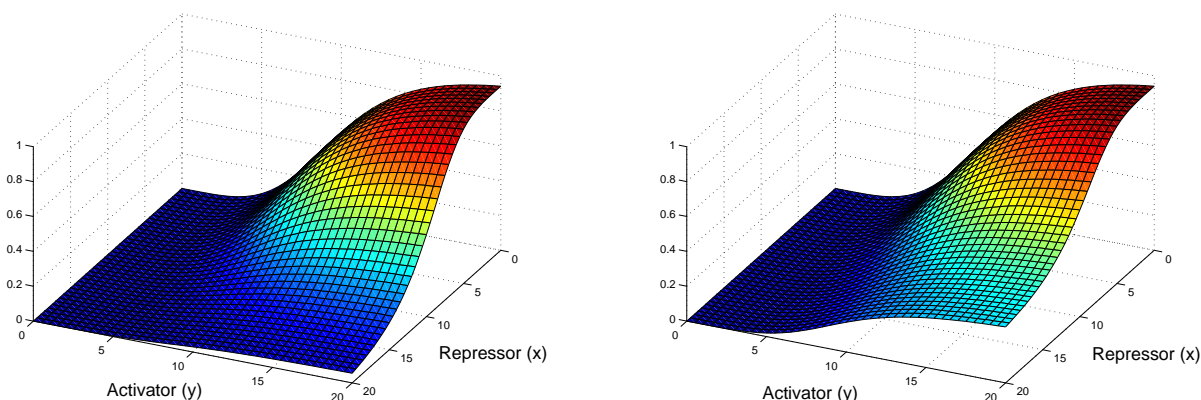


Figure 38: Transcription rate function in the presence of an activator and an inhibitor. Left:  $b_1 = 1$ ,  $b_2 = 0$ ,  $b_2 = O$ ,  $K_1 = 10$ ,  $K_2 = 10$ , and  $n = 4$ . Right: idem except  $b_2 = 0.3$ .

These results can be generalized. The transcription rate function can often be described by the ratio of polynomials of the active concentrations of the transcription factors  $X_i$ , with  $i = 1, 2, \dots, n$ . For example,

$$v = \frac{\sum_i b_i (X/K_i)^{n_i}}{1 + \sum_i b_i (X/K_i)^{m_i}} \quad (178)$$

The parameter  $K_i$  is the activation or repression coefficient for the transcription factor  $X_i$ , while  $b_i$  is its maximal contribution to expression, and the Hill coefficients are  $n = m$  for activation and  $n = 0, m > 0$  for repression. These types of functions have been found suitable to describe experimentally determined input function (Setty et al, 2003). More sophisticated expressions are also possible if the transcription factors interact with each other at the protein level (Buchler et al 2003).

## 4 Appendix

### 4.1 Quasi-steady state approximation

In this appendix we demonstrate how the fact that the enzyme is much lower than the substrate leads to the approximation that the concentration of the complex C does not change significantly with time, i.e. that:

$$E \ll S \Rightarrow \frac{dC}{dt} \simeq 0 \quad (179)$$

First, we define dimensionless variable as follows:

$$s = \frac{S}{S_0}, e = \frac{E}{E_T}, \text{ and } c = \frac{C}{E_T} \quad (180)$$

we also define a new time:

$$\tau = k_1 E_T t \quad (181)$$

Because the total concentration in enzyme is fixed ( $E + C = E_T$ ), we have

$$e + c = 1 \quad (182)$$

We start by expressing  $dS/dt$  in terms of dimensionless variables. With the definitions (180),

$$\frac{dS}{dt} = -k_1 S E + k_{-1} C \quad (183)$$

becomes

$$\frac{ds}{d\tau} = -se + \alpha c = -s + c(s + \alpha) \quad (184)$$

where

$$\alpha = \frac{k_{-1}}{k_1 S_0}$$

Similarly, the evolution equation for C,

$$\frac{dC}{dt} = k_1 S E - (k_{-1} + k_2) C \quad (185)$$

becomes

$$\frac{E_T}{S_0} \left( \frac{dc}{d\tau} \right) = se - \frac{\beta}{k_1 S_0} c = s(1 - c) - \frac{\beta}{k_1 S_0} c \quad (186)$$

where

$$\beta = k_{-1} + k_2$$

The hypothesis that the enzyme is much lower than the substrate can be expressed as:

$$\epsilon = \frac{E_T}{S_0} \ll 1 \quad (187)$$

Expressing  $\epsilon$  in eq. 186 we get

$$\epsilon \frac{dc}{d\tau} = s - c \left( s + \frac{\beta}{k_1 S_0} \right) \quad (188)$$

At the limit

$$\epsilon \rightarrow 0 \quad (189)$$

we have

$$\epsilon \frac{dc}{d\tau} = s - c \left( s + \frac{\beta}{k_1 S_0} \right) \simeq 0 \quad (190)$$

From eq. 190, this we deduce:

$$c = \frac{s}{\gamma + s} \quad (191)$$

where

$$\gamma = \frac{\beta}{k_1 S_0}$$

and, going back to the original variable, we find

$$C = \frac{E_T S}{K_m + S} \quad (192)$$

where

$$K_m = \frac{\beta}{k_1} = \frac{k_{-1} + k_2}{k_1}$$

which is the michaelian constant.

Restarting now from eq 183, where we replace  $c$  by its expression (eq. 191) we obtain

$$\frac{ds}{d\tau} = -s + \frac{s}{\gamma + s}(s + \alpha) = \frac{s(\alpha - \gamma)}{\gamma + s} \quad (193)$$

We see that:

$$\alpha - \gamma = -\frac{k_2}{k_1 S_0} \quad (194)$$

and therefore

$$\frac{ds}{d\tau} = -\frac{k_2}{k_1 S_0} \frac{S}{K_m + S} \quad (195)$$

$$\frac{dS}{d(k_1 E_T t)} = -\frac{k_2}{k_1} \frac{S}{K_m + S} \quad (196)$$

$$\frac{dS}{dt} = -k_2 \frac{ES}{K_m + S} = -V_{max} \frac{S}{K_m + S} \quad (197)$$

Hence, the rate at which the substrate decreases is equal to the rate at which the product appears

$$-\frac{dS}{dt} = \frac{dP}{dt} = v \quad (198)$$



and

$$v = V_{max} \frac{S}{K_m + S} \quad (199)$$

where

$$K_m = \frac{k_{-1} + k_2}{k_1} \text{ and } V_{max} = k_2 E$$

Note that

$$k_2 \rightarrow 0 \Rightarrow K_m \rightarrow K_S = \frac{k_{-1}}{k_1} \quad (200)$$

When the reaction is fast,  $K_M$  tends to the equilibrium constant of the first reaction.

If  $S \ll K_m$ , we observe a first order kinetics (linear relation between  $v$  and  $S$ ):

$$v = kS \quad (201)$$

where

$$k = \frac{V_{max}}{K_m}$$

If  $S \gg K_m$ , we observe a zero-order kinetics (constant rate  $v$ ):

$$v = V_{max} \quad (202)$$

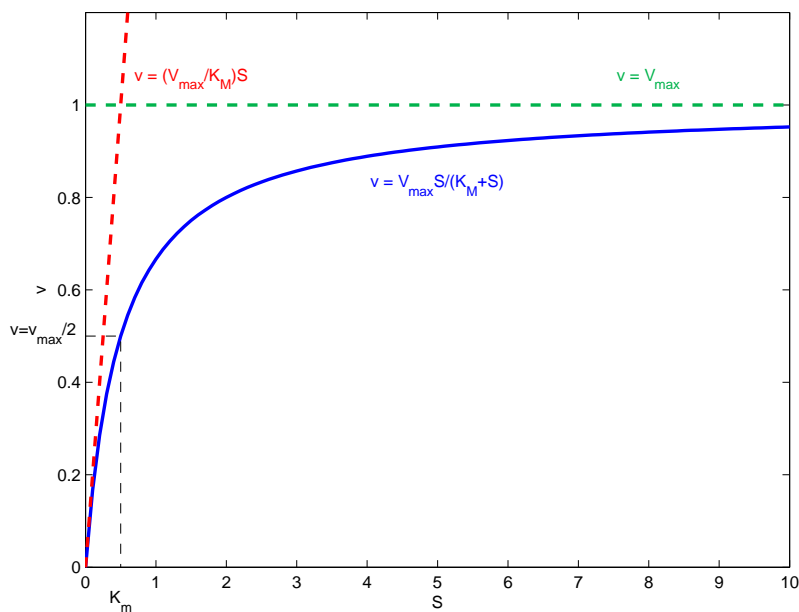


Figure 39: Michaelis-Menten kinetics

## 4.2 Validity of the quasi-steady state approximation

In deriving the Michaelis-Menten equation, it was assumed that a steady state would be reached in which  $dC/dt = 0$ . In fact Eq. for  $dC/dt$  in Eqs. (38) is readily integrable if  $S$  is treated as a constant, and it is instructive to derive a rate equation without making the steady state assumption, because this sheds light on the validity of the assumption (Cornish-Bowden, 1995, p. 29). Separating the two variables  $C$  and  $t$ , we have

$$\int \frac{dC}{k_1 E_T S - (k_1 S + k_{-1} + k_2) C} = \int dt \quad (203)$$

Integrating both sides, we find:

$$\frac{\ln[k_1 E_T S - (k_1 S + k_{-1} + k_2) C]}{-(k_1 S + k_{-1} + k_2)} = t + \alpha \quad (204)$$

At the instant when the reaction starts, there has not been enough time to produce any ES complex, i.e.  $C = 0$  when  $t = 0$  and hence:

$$\alpha = \frac{\ln(k_1 E_T S)}{-(k_1 S + k_{-1} + k_2)} \quad (205)$$

Thus,

$$\ln \left[ \frac{k_1 E_T S - (k_1 S + k_{-1} + k_2) C}{k_1 E_T S} \right] = -(k_1 S + k_{-1} + k_2) t \quad (206)$$

Taking exponentials of both sides, we have

$$1 - \frac{(k_1 S + k_{-1} + k_2) C}{k_1 E_T S} = e^{-(k_1 S + k_{-1} + k_2) t} \quad (207)$$

and solving for  $C$  we have

$$C = \frac{k_1 E_T S [1 - e^{-(k_1 S + k_{-1} + k_2) t}]}{k_1 S + k_{-1} + k_2} \quad (208)$$

The rate is given by  $v = k_2 C$ , and thus, substituting  $v_{max} = k_2 E_T$  and  $K_M = (k_{-1} + k_2)/k_1$ , we have:

$$v = \frac{v_{max} S [1 - e^{-(k_1 S + k_{-1} + k_2) t}]}{k_M + S} \quad (209)$$

When  $t$  becomes very large the exponential term approaches 0 and Eqs. (209) becomes identical to the Michaelis-Menten Eq. (47). How large  $t$  must be for this to happen depends on the magnitude of  $(k_1 S + k_{-1} + k_2)$ . If it is of the order of  $1000 \text{ s}^{-1}$  (a reasonable value in practice), then the exponential term is less than 0.01 for value greater than 5 ms. In other words Eq. (209) should become indistinguishable from the Michaelis-Menten equation after a few milliseconds.

### 4.3 Comparison of developed vs compact Michaelis-Menten kinetics

Numerical simulation of the “developed” reactional scheme (Eqs. 38) and the Michaelis-Menten kinetics (eq. 47) shows a very good agreement (Fig. 40).

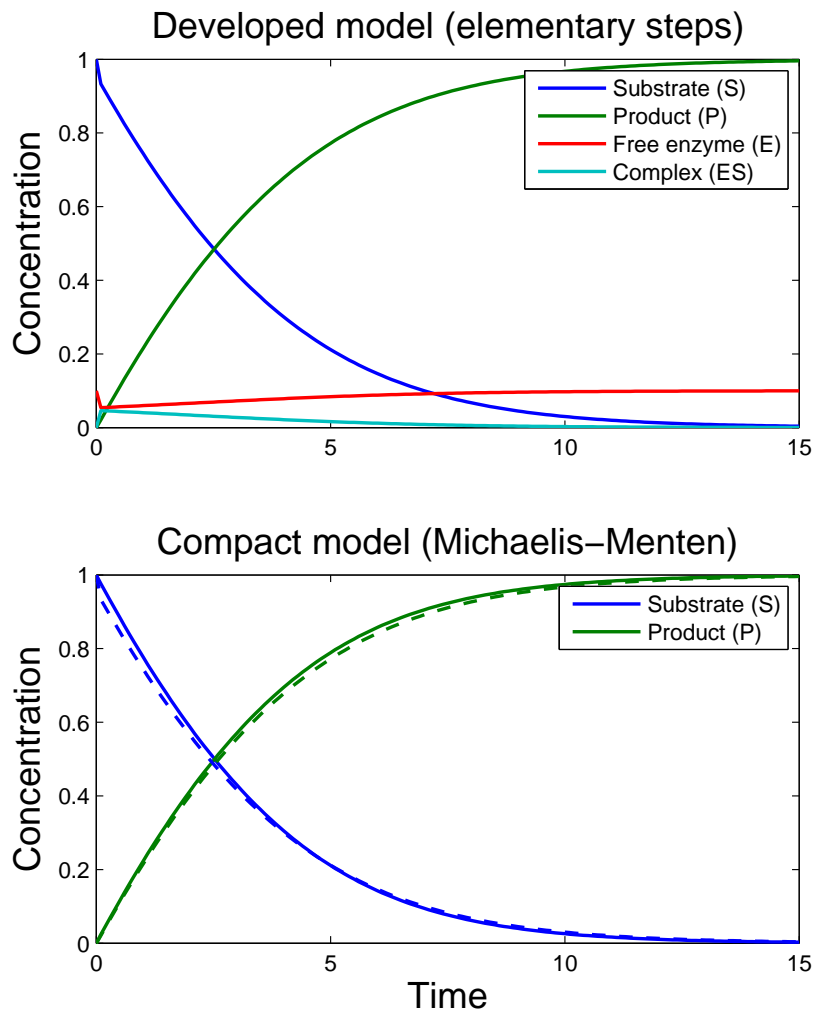
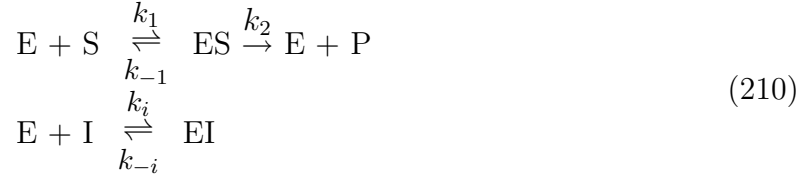


Figure 40: Comparison of developed vs compact Michaelis-Menten kinetics. Parameter values:  $S_0 = 1$ ,  $P_0 = 0$ ,  $E_T = 0.1$ ,  $k_1 = 50$ ,  $k_{-1} = 50$ ,  $k_2 = 5$ ,  $K_M = (k_{-1} + k_2)/k_1$ ,  $v_{max} = k_2 E_T$ .

## 4.4 Competitive inhibition

We show here how to derive the enzyme kinetics equation in presence of competitive inhibition. The cases of other types of inhibition can be treated in a similar way.

The reaction scheme is:



First, let's define the equilibrium constant

$$K_I = \frac{k_{-i}}{k_i} = \frac{E * I}{EI} \quad (211)$$

Thus

$$EI = \frac{E * I}{K_I} \quad (212)$$

Using the quasi-steady state assumption

$$\frac{dES}{dt} = 0 \quad (213)$$

we find

$$\begin{aligned} k_1 E * S &= (k_{-1} + k_2) ES \\ E &= \frac{(k_{-1} + k_2) ES}{k_1 S} \end{aligned} \quad (214)$$

Then, combining eqs. (212) and (214), we get

$$\begin{aligned} E_{tot} &= ES + E + EI \\ &= ES + E + \frac{E * I}{K_I} \\ &= ES + E \left(1 + \frac{I}{K_I}\right) \\ &= ES + \frac{(k_{-1} + k_2)}{K_I} \\ &= ES + \frac{(k_{-1} + k_2) ES}{k_1 S} \left(1 + \frac{I}{K_I}\right) \\ &= ES \left(1 + \frac{(k_{-1} + k_2)}{k_1 S} \left(1 + \frac{I}{K_I}\right)\right) \end{aligned} \quad (215)$$

Finally the rate of production of the product P is

$$\begin{aligned}
 \frac{dP}{dt} &= k_2 * ES \\
 &= k_2 \frac{E_{tot}}{1 + \frac{(k_{-1} + k_2)}{k_1 S} \left(1 + \frac{I}{K_I}\right)} \\
 &= \frac{k_2 E_{tot} S}{S + \frac{(k_{-1} + k_2)}{k_1 S} \left(1 + \frac{I}{K_I}\right)} \tag{216}
 \end{aligned}$$

Defining:

$$v_{max} = k_2 E_{tot} \tag{217}$$

$$K_M = \frac{(k_{-1} + k_2)}{k_1} \tag{218}$$

$$\tag{219}$$

Eq. (216) can be rewritten:

$$v = v_{max} \frac{S}{K_M \left(1 + \frac{I}{K_I}\right) + S} \tag{220}$$

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